

# A Smooth and Algebraic Invariants of a Group Action: Local and Global Constructions.

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**Abstract:** We provide an algebraic formulation of the moving frame method for constructing local smooth invariants on a manifold under an action of a Lie group. This formulation gives rise to algorithms for constructing rational and replacement invariants. The latter are algebraic over the field of rational invariants and play a role analogous to Cartan's normalized invariants in the smooth theory. The algebraic algorithms can be used for computing fundamental sets of differential invariants.

Smooth construction	Algebraic construction
<p>Lie grp. <math>\mathcal{G} \curvearrowright M</math> smooth manifold over <math>\mathbb{R}</math>  smooth, local, semi-regular action</p>	<p><b>Consider</b>  Alg. grp. <math>\mathcal{G} \curvearrowright \mathcal{Z} \subset \mathbb{K}^n</math> affine variety  rational action</p>
<p><math>\mathcal{F}(M)^{\mathcal{G}}</math>-smooth invariants</p>	<p><math>\mathbb{K}(\mathcal{Z})^{\mathcal{G}}</math> – rational invariants</p>
<p>local cross-section to the orbits</p>	<p><b>Construct</b>  graph-section</p>
<p style="text-align: center;">↓</p> <p>moving frame map <math>\rho : M \rightarrow \mathcal{G}</math></p>	<p style="text-align: center;">↓</p> <p>reduced Gröbner basis</p>
<p style="text-align: center;">↓</p> <p>fundamental set for <math>\mathcal{F}(M)^{\mathcal{G}}</math>  normalized inv. with replacement property</p>	<p style="text-align: center;">↓</p> <p>finite generating set for <math>\mathbb{K}(\mathcal{Z})^{\mathcal{G}}</math>  replacement inv. that are <math>\overline{\mathbb{K}(\mathcal{Z})^{\mathcal{G}}}</math>-tuples</p>
<p style="text-align: center;">↓</p> <p>projection <math>\iota : \mathcal{F}(M) \rightarrow \mathcal{F}(M)^{\mathcal{G}}</math></p>	<p style="text-align: center;">↓</p> <p>projection <math>\iota : \mathbb{K}(\mathcal{Z}) \rightarrow \overline{\mathbb{K}(\mathcal{Z})^{\mathcal{G}}}</math></p>

## Motivation

Smooth construction



Algebraic construction

- $\longrightarrow$  new approaches for computation and study of algebraic invariants.
- $\longleftarrow$  computational methods for analyzing the structure of differential algebra of invariants.

## Some Applications

- Symmetry reductions of differential and algebraic equations
- Equivalence problems (e.g. computer image recognition)

**Smooth construction:**  $\mathcal{G}$  is a Lie group,  $M$  is a smooth manifold.

**Local action**  $\mathcal{G} \curvearrowright M$  is a smooth map  $g: \Omega \rightarrow M$ , where  $\Omega \supset \{e\} \times M$  is open in  $\mathcal{G} \times M$  s. t.

(i)  $g(e, \bar{z}) = \bar{z}, \forall \bar{z} \in M$

(ii)  $g(\bar{\mu}, g(\bar{\lambda}, \bar{z})) = g(\bar{\mu}\bar{\lambda}, \bar{z})$ , for all  $\bar{z} \in M$  and  $\bar{\lambda}, \bar{\mu} \in \mathcal{G}$  s. t.  $(\bar{\lambda}, \bar{z})$  and  $(\bar{\mu} \cdot \bar{\lambda}, \bar{z})$  are in  $\Omega$ .

( *Notation:  $g(\bar{\lambda}, \bar{z}) = \bar{\lambda} \cdot \bar{z}$  )*

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**Local smooth invariants:**  $f \in \mathcal{F}(\mathcal{U})$ , where  $\mathcal{U} \subset M$  is an open subset, s.t.  $f(g(\bar{\lambda}, \bar{z})) = f(\bar{z}), \forall (\bar{\lambda}, \bar{z})$  in an open subset of  $\Omega$  containing  $e \times \mathcal{U}$ .

**Infinitesimal criterion:**  $\mathbf{v}(f)(\bar{z}) = 0 \forall \bar{z} \in \mathcal{U}, \forall$  infinitesimal generators  $\mathbf{v}$  of  $\mathcal{G} \curvearrowright M$ .

(  *$\mathcal{G}$  connected,  $\mathbf{v}(f)(\bar{z}) = 0, \forall \bar{z} \in M \Rightarrow f$  is global invariant* )

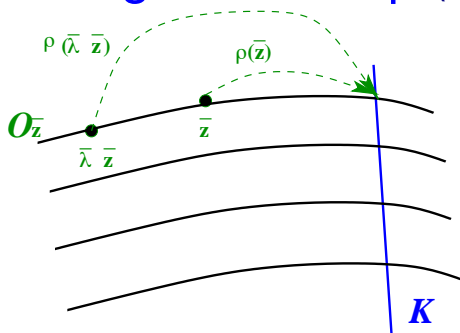
Smooth construction:

Local cross-section  $\mathcal{K}$  on  $\mathcal{U} \subset M$  is a submanifold, s. t.

- $T_{\bar{z}}\mathcal{K} \oplus T_{\bar{z}}\mathcal{O}_{\bar{z}} = T_{\bar{z}}M, \quad \forall \bar{z} \in \mathcal{K}$  (transversality condition)
- $\mathcal{K}$  intersects each connected component of  $\mathcal{O}_{\bar{z}} \cap \mathcal{U}$  at the unique point.

$\mathcal{G} \curvearrowright M$  semi. reg. (i.e.  $\exists s, \forall \bar{z} \in M \dim \mathcal{O}_{\bar{z}} = s$ )  $\xRightarrow{\text{Frobenius Thm.}} \forall \bar{z} \in M \exists \mathcal{K} \ni \bar{z}$ .

Moving frame map (Fels, Olver (1999)) defined by  $\rho(\bar{z}) \cdot \bar{z} \in \mathcal{K}$



$\mathcal{G} \curvearrowright M$  free  $\Rightarrow \rho$  is smooth,  $\mathcal{G}$ -equivariant:

$$\rho(\bar{\lambda} \cdot \bar{z}) \cdot (\bar{\lambda} \cdot \bar{z}) = \rho(\bar{z}) \cdot \bar{z} \xrightarrow{\text{freeness}} \rho(\bar{\lambda} \cdot \bar{z}) = \rho(\bar{z}) \cdot \bar{\lambda}^{-1}$$

Smooth construction: Invariantization:  $\iota: \mathcal{F}(\mathcal{U}) \rightarrow \mathcal{F}^{\mathcal{G}}(\mathcal{U})$

- Defined via the moving frame map  $\rho$  (Fels, Olver (1999))

$$\iota f(\bar{z}) = f(\rho(\bar{z}) \cdot \bar{z})$$

$\rho$  is non-constructive – existence relies on the implicit function theorem

- Defined as restriction to a cross-section  $\mathcal{K}$

$$\forall \bar{z} \in \mathcal{U} \quad \iota f(\bar{z}) = f(\bar{z}_0), \text{ where } \bar{z}_0 = \mathcal{O}_{\bar{z}}^0 \cap \mathcal{K}.$$

- $\mathcal{K}$  is constructive –  $\forall \bar{z} \in \mathcal{Z}$  one can construct c.s. defined as a level set of  $n - s$  coord. functions.
- freeness is not required.

THEOREM 1.

- If the action is free both definitions are equivalent
- $\iota f$  is the unique smooth local invariant s.t.  $\iota f|_{\mathcal{K}} = f|_{\mathcal{K}}$

## Smooth construction: Normalized and fundamental invariants

DEFINITION.

If  $z = (z_1, \dots, z_n)$  are coordinate functions on  $\mathcal{U}$  then  $\iota z_1, \dots, \iota z_n$  are called normalized invariants

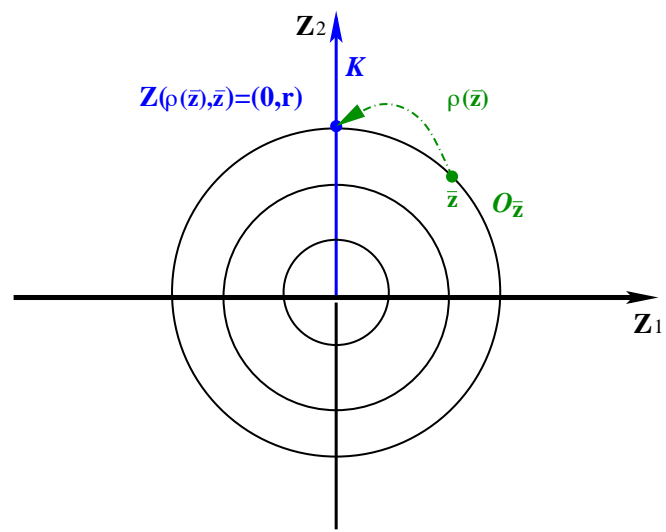
THEOREM 2.

- **Invariantization:** If  $f \in \mathcal{F}(\mathcal{U})$  then  $\iota f(z_1, \dots, z_n) = f(\iota z_1, \dots, \iota z_n) \in \mathcal{F}(\mathcal{U})^{\mathcal{G}}$
- **Replacement:** If  $f \in \mathcal{F}(\mathcal{U})^{\mathcal{G}}$  then  $f(z_1, \dots, z_n) = f(\iota z_1, \dots, \iota z_n) = \iota f(z)$ .
- **Fundamental set:** Let  $\dim \mathcal{O}_{\bar{z}} = s, \forall \bar{z} \in \mathcal{U}$ , then  $\{\iota z_1, \dots, \iota z_n\}$  contains  $n - s$  functionally independent local inv., s.t. any  $f \in \mathcal{F}(\mathcal{U})^{\mathcal{G}}$  can be locally expressed as function of these invariants in a unique way.

**Smooth Example 1:**  $SO(2) = \left\{ \begin{pmatrix} \cos \phi & -\sin \phi \\ \sin \phi & \cos \phi \end{pmatrix} \right\} \curvearrowright M = \mathbb{R}^2 / \{(0,0)\}$

**Action:**  $Z_1 = \cos(\phi) z_1 - \sin(\phi) z_2, \quad Z_2 = \sin(\phi) z_1 + \cos(\phi) z_2$

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**Cross-section:**

$$\mathcal{K} = \{(z_1, z_2) | z_1 = 0, z_2 > 0\} \Rightarrow$$

**Moving frame map is defined by  $Z_1 = 0$**

$$\text{i.e. } \rho(z) = \begin{pmatrix} \frac{z_2}{\sqrt{z_1^2 + z_2^2}} & -\frac{z_1}{\sqrt{z_1^2 + z_2^2}} \\ \frac{z_1}{\sqrt{z_1^2 + z_2^2}} & \frac{z_2}{\sqrt{z_1^2 + z_2^2}} \end{pmatrix}$$

**Invariantization:**  $f(z_1, z_2) \in \mathcal{F}(M) \rightarrow$

$$\iota f(z) = f(\rho(z) \cdot z) = f(0, \sqrt{z_1^2 + z_2^2}) \in \mathcal{F}^G$$

**Normalized invariants:**  $\iota z_1 = 0,$

$$\iota z_2 = \sqrt{z_1^2 + z_2^2} = r \text{ (fundamental invariant)}$$

**Replacement property:**  $f \in \mathcal{F}(M)^G \Rightarrow f(z) = f(\iota z_1, \iota z_2) = f(0, r)$  i.e.  
 $z_1^2 + z_2^2 = (\iota z_1)^2 + (\iota z_2)^2 = 0^2 + r^2$

**Restrictions to the cross-section:**  $\iota f|_{\mathcal{K}} = f|_{\mathcal{K}} = f(0, r)$

**Smooth Example 2:**  $SE(2) = SO(2) \ltimes \mathbb{R}^2 \curvearrowright$  on plane curves  $y = y(x)$ :

Action:  $X = \cos(\phi)x - \sin(\phi)y + a$ ,  $Y = \sin(\phi)x + \cos(\phi)y + b$

Prolongation to derivatives up to second order:

$$Y_1 = \frac{\sin(\phi) + \cos(\phi)y_1}{\cos(\phi) - \sin(\phi)y_1}, \quad Y_2 = \frac{y_2}{(\cos(\phi) - \sin(\phi)y_1)^3}$$

Cross-section:  $\mathcal{K} = \{(x, y, y_1, y_2) | x = 0, y = 0, y_1 = 0, y_2 > 0\} \subset \mathbb{R}^4$

Moving frame map is defined by:  $X = 0, Y = 0, Y_1 = 0 \Rightarrow$

$$\cos \phi = \frac{1}{\sqrt{y_1^2 + 1}}, \quad \sin \phi = -\frac{y_1}{\sqrt{1 + y_1^2}}, \quad a = -\frac{x + y_1 y}{\sqrt{1 + y_1^2}}, \quad b = \frac{y_1 x - y}{\sqrt{1 + y_1^2}}.$$

Normalized invariants:  $\iota x = 0, \iota y = 0, \iota y_1 = 0,$

$\iota y_2 = \frac{y_2}{(1 + y_1^2)^{3/2}}$  is curvature –differential invariant.

**Algebraic construction:**  $\mathcal{G}$  is an alg. group,  $\mathcal{Z}$  is an affine variety.

Rational action  $\mathcal{G} \curvearrowright \mathcal{Z}$  is a rational map  $g: \mathcal{G} \times \mathcal{Z} \rightarrow \mathcal{Z}$  s. t.

(i)  $g(e, \bar{z}) = \bar{z}, \forall \bar{z} \in \mathcal{Z}$

(ii)  $g(\bar{\mu}, g(\bar{\lambda}, \bar{z})) = g(\bar{\mu} \bar{\lambda}, \bar{z}), \forall \bar{\lambda}, \bar{\mu} \in \mathcal{G}$  and  $\forall \bar{z} \in \mathcal{Z}$  s.t.  $g(\bar{\lambda}, \bar{z})$  and  $g(\bar{\mu} \bar{\lambda}, \bar{z})$  are defined.

( *Notation:*  $g(\bar{\lambda}, \bar{z}) = \bar{\lambda} \cdot \bar{z}$  )

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Rational invariants:  $f \in \mathbb{K}(\mathcal{Z})$  s.t.  $f(g(\bar{\lambda}, \bar{z})) = f(\bar{z}), \forall \bar{z} \in \mathcal{Z}$  and  $\forall \bar{\lambda} \in \mathcal{G}$  s.t.  $g(\bar{\lambda}, \bar{z})$  is defined.

Algebraic construction: Notation:  $\bar{S}$  is Zariski closure of set  $S$

Graph of the action  $\mathcal{O} = \overline{\{(\bar{z}, \bar{z}') \in \mathcal{Z} \times \mathcal{Z} \mid \exists \bar{\lambda} \in \mathcal{G} : \bar{z}' = \bar{\lambda} \cdot \bar{z}\}} \leftrightarrow$  ideal:

$$\mathcal{O} \subset \mathbb{K}[\mathcal{Z} \times \mathcal{Z}]$$

extension:  $\boxed{\mathcal{O}^e \subset \mathbb{K}(\mathcal{Z})[\mathcal{Z}]}$

Orbit:  $\mathcal{O}_{\bar{z}} = \overline{\{\bar{z}' \in \mathcal{Z} \mid \exists \bar{\lambda} \in \mathcal{G} : \bar{z}' = \bar{\lambda} \cdot \bar{z}\}} \leftrightarrow$  ideal:  $\mathcal{O}_{\bar{z}} \subset \mathbb{K}[\mathcal{Z}]$

Cross-section of degree  $d$ : an irreducible subvariety  $\mathcal{K} \subset \mathcal{Z}$  s.t.  $\mathcal{O}_{\bar{z}} \cap \mathcal{K}$  consists of  $d$  simple points  $\forall \bar{z}$  in a dense subset of  $\mathcal{Z}$  (transversality condition)

↑

ideal:  $K$  is prime, s.t.  $\text{codim} K = \max_{\bar{z}} \dim \mathcal{O}_{\bar{z}} = s$  and  $\boxed{I^e = \mathcal{O}^e + K \subset \mathbb{K}(\mathcal{Z})[\mathcal{Z}]}$  is radical **zero-dimensional** (transversality cond.)

Graph-section:  $\mathcal{I} = \{(\bar{z}, \bar{z}') \in \mathcal{Z} \times \mathcal{K} \mid \exists \bar{\lambda} \in \mathcal{G} : \bar{z}' = \bar{\lambda} \cdot \bar{z}\} \leftrightarrow$  ideal:  $I = \mathcal{O} + K \subset \mathbb{K}[\mathcal{Z} \times \mathcal{Z}]$

Algebraic construction: Generating set of  $\mathbb{K}(\mathcal{Z})^{\mathcal{G}}$ .

THEOREM 3:

Coeff. of a reduced Gröbner basis  $Q$  of either  $O^e$  or  $I^e$  generate  $\mathbb{K}(\mathcal{Z})^{\mathcal{G}}$ .

Ideas of the proof:

- If  $(\bar{z}, \bar{z}') \in \mathcal{O} \Rightarrow (\bar{\lambda} \cdot \bar{z}, \bar{z}') \in \mathcal{O}, \forall \bar{\lambda} \in \mathcal{G}$ . Hilbert's Nullstellensatz & uniqueness of the reduced  $Q \rightarrow$  coeff. of  $Q$  are in  $\mathbb{K}(\mathcal{Z})^{\mathcal{G}}$
- Rewriting algorithm to express  $f(z) = \frac{p(z)}{q(z)} \in \mathbb{K}(\mathcal{Z})^{\mathcal{G}}$  in terms of generators by computing normal forms of  $p$  and  $q$  w.r.t.  $Q$ .

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Previous work. **Rosenlicht (1956)**:  $\forall$  subset set of  $\mathbb{K}(\mathcal{Z})^{\mathcal{G}}$  that separates orbits generates  $\mathbb{K}(\mathcal{Z})^{\mathcal{G}}$ ; coeffs. of Chow form of  $O^e$  have this property.

**Vinberg, Popov (1989)**: if coeff. of a generating set of  $O^e$  are in  $\mathbb{K}(\mathcal{Z})^{\mathcal{G}}$ , then they generate  $\mathbb{K}(\mathcal{Z})^{\mathcal{G}}$ ;  $\exists$  such generating set.

**Beth, Müller-Quade (1999)**: rewriting algorithm for linear actions.

**Contribution**: Simple algorithm applicable to both  $O^e$  and  $I^e$ .  $\dim I^e = 0 \Rightarrow$  computational advantage.

## Algebraic construction: Replacement invariants

LEMMA. Let  $Q$  be a reduced Gröbner basis of the graph-section ideal  $I^e = (O^e + K) \subset \mathbb{K}(\mathcal{Z})[\mathcal{Z}]$ . Then

- $Q$  is a reduced Gröbner basis of  $I^{\mathcal{G}} = I^e \cap \mathbb{K}(\mathcal{Z})^{\mathcal{G}}[\mathcal{Z}]$ .
- $I^{\mathcal{G}} \subset \mathbb{K}(\mathcal{Z})^{\mathcal{G}}[\mathcal{Z}]$  is **zero-dimensional and prime**.
- If c.-s.  $\mathcal{K}$  has degree  $d$  then  $I^{\mathcal{G}}$  has  $d$  simple  $\overline{\mathbb{K}(\mathcal{Z})^{\mathcal{G}}}$ -zeros  $\xi^{(i)} : [\overline{\mathbb{K}(\mathcal{Z})^{\mathcal{G}}}]^n \rightarrow \mathcal{Z}$ ,  $i = 1..d$ , (called **replacement invariants** associated with  $\mathcal{K}$ .)

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THEOREM 4. Let  $\xi^{(i)}$ ,  $i = 1..d$ , be replacement invariants associated with  $\mathcal{K}$  of degree  $d$ . Then

- $f(z) \in \mathbb{K}(\mathcal{Z})^{\mathcal{G}} \Rightarrow f(z) = f(\xi^{(i)})$  for  $i = 1..d$ . (replacement)
- $\mathbb{K}(\mathcal{K}) \cong \mathbb{K}(\xi^{(i)})$ ,  $i = 1..d$  is the extension of degree  $d$  of  $\mathbb{K}(\mathcal{Z})^{\mathcal{G}}$ .
- $\iota_i : \mathbb{K}[\mathcal{Z}]_{\mathcal{K}} \rightarrow \overline{\mathbb{K}(\mathcal{Z})^{\mathcal{G}}} : \iota_i f = f(\xi^{(j)})$  for  $j = 1..d$  is computable projection (invariantization)

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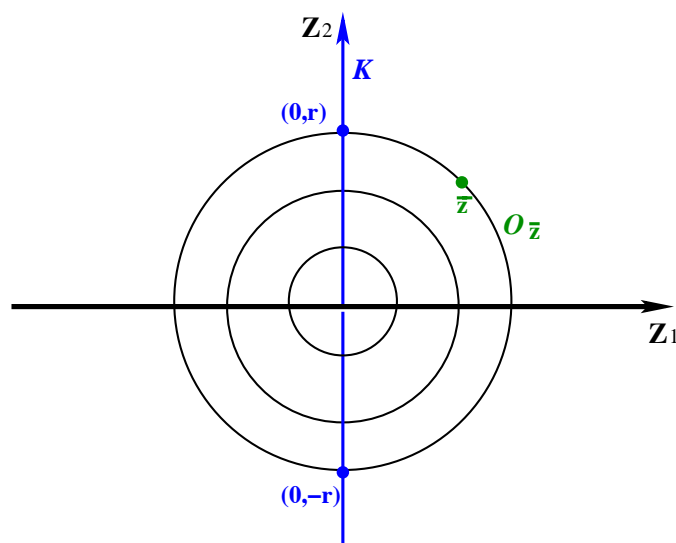
COROLLARY. If  $d = 1$  there is a unique rational replacement invariant  $\xi : [\overline{\mathbb{K}(\mathcal{Z})^{\mathcal{G}}}]^n \rightarrow \mathcal{Z}$ , that provides a generating set of  $\mathbb{K}(\mathcal{Z})^{\mathcal{G}}$  (cf. [Vinberg, Popov \(1989\)](#)):

$$\mathbb{K}(\mathcal{Z})^{\mathcal{G}} \cong \mathbb{K}(\xi) \cong \mathbb{K}(\mathcal{K})$$

Algebraic Example 1: (rotation)  $SO(2) \curvearrowright \mathbb{K}^2$

Group ideal:  $G = (\lambda_1^2 + \lambda_2^2 - 1) \subset \mathbb{K}[\lambda_1, \lambda_2]$

Action ideal:  $J = (Z_1 - (\lambda_1 z_1 - \lambda_2 z_2), Z_2 - (\lambda_2 z_1 + \lambda_1 z_2)) + G$



Graph ideal:  $O = J \cap K[\mathcal{Z} \times \mathcal{Z}]$

$Q = \{Z_1^2 + Z_2^2 - (z_1^2 + z_2^2)\}$  is rGB for  $O$  and  $O^e$ .

Cross-section ideal (of degree 2):

$K = (Z_1)$

Graph-section ideal:  $I = O + K$

$Q = \{Z_1, Z_2^2 - (z_1^2 + z_2^2)\}$  is rGB for  $I$  and  $I^e$

Replacement invariants: are  $\overline{\mathbb{K}(\mathcal{Z})^{\mathcal{G}}}$  roots of  $I^e$ :  $(\xi_1^{\pm}, \xi_2^{\pm}) = (0, \pm r)$

Replacement property:

$f \in \mathbb{K}(\mathcal{Z})^{\mathcal{G}} \Rightarrow f(z) = f(\xi^{\pm})$  i.e.  $z_1^2 + z_2^2 = (\xi_1^{\pm})^2 + (\xi_2^{\pm})^2$

**Algebraic Example 2:**  $SE(2) \curvearrowright$  plane curves.

Notation:  $\lambda = (\lambda_1, \lambda_2, \lambda_3, \lambda_4)$ ,  $z = (x, y, y_1, y_2)$ ,  $Z = (X, Y, Y_1, Y_2)$

Group ideal:  $G = (\lambda_1^2 + \lambda_2^2 - 1) \subset \mathbb{K}[\lambda]$

Action ideal:

$$J = \left( X - (\lambda_1 x - \lambda_2 y + \lambda_3), Y - (\lambda_2 x + \lambda_1 y + \lambda_4), \right. \\ \left. Y_1 - \frac{\lambda_2 + \lambda_1 y_1}{\lambda_1 - \lambda_2 y_1}, Y_2 - \frac{y_2}{(\lambda_1 - \lambda_2 y_1)^3} \right) + G \subset \mathbb{K}[\lambda, z, Z]$$

Cross-section ideal:  $K = (X, Y, Y_1)$

Graph-section ideal:  $\left\{ X, Y, Y_1, Y_2^2 - \frac{y_2^2}{(1+y_1^2)^3} \right\}$  is rGB for  $I = (J + K) \cap \mathbb{K}[z, Z]$ ,  $I^e \in \mathbb{K}(z)[Z]$  and  $I^G \in \mathbb{K}(\mathcal{Z})^{\mathcal{G}}[Z]$

Replacement Invariants:  $\overline{\mathbb{K}(\mathcal{Z})^{\mathcal{G}}}$ -roots if  $I^e$ :  $\xi_1^{\pm} = (0, 0, 0, \pm\kappa)$ , where  $\kappa = \frac{y_2}{(1+y_1^2)^{3/2}}$  is curvature.