

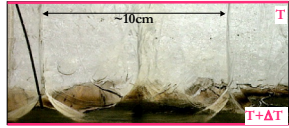
Viscous entrainment of thin tendrils from stratified liquid layers

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Motivation & Context

Experiments: 2-layer thermal convection of miscible liquids



Localized tendrils persist & stabilize overall flow.

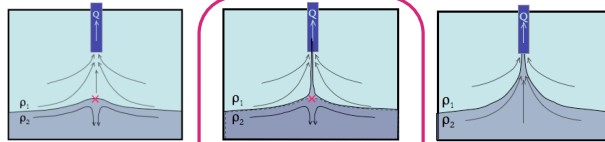
Mixing by flow through entrained tendrils.

tendril radius \ll imposed length scales

Experimental studies: Davaille, *JFM* (1999); Le Bars and Davaille, *JFM* (2004) Jellinek and Manga, *Reviews of Geophysics*, 42 (2004).

ENTRAINMENT REGIMES

withdrawal flux, Q , increasing \rightarrow



hump
no entrainment
layers recirculate
stagnation point at tip

thin tendril
liquid at surface entrained
stagnation point at base

thick spout
bulk upwards flow

thick spout state studied theoretically (Sleep, *Geophys. J.* 1988)

Recent experiments show existence of **stagnation point** for **thin tendrils** (Davaille, 2006; Case and Nagel, *PRL* 2007).

Need a simple understanding:

What sets the size of the tendril?
What is the flow through the tendril?

Entrainment in a Model Flow

Drive entrainment with straining flow in upper layer, consistent w/ stagnation pt $U = (-Er/2, 0, Ez)$, where E is the strain rate (s^{-1})

Flow induced in lower layer via viscous coupling at interface.

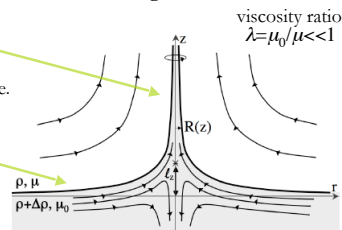
Steady-state flow dynamics separate into **two distinct regions**:

1) Near tendril

Long & slender interface.
Ext. viscous stress \sim interior pressure.

2) Far field, away from tendril

Interface almost flat.
Ext. viscous stress \sim stratification.



Simple Scaling Arguments

Natural vertical scale: balance between viscous stress & stratification:

$$\ell_z = 2\mu E / \Delta\rho g$$

To find radial length scale, look at vertical flow inside tendril. 3 contributions:

- 1) upwards plug flow, driven by exterior $u_r(r, z) = Ez$
- 2) Poiseuille flow from vertical pressure gradient $u_r(r, z) = -\frac{dP_0/dz}{4\mu_0}(R^2(z) - r^2)$
- 3) drainage due to hydrostatic pressure gradient $u_r(r, z) = -\frac{\Delta\rho g}{4\mu_0}(R^2(z) - r^2)$

Interior pressure, P_0 , must balance inward press from exterior viscous stress, in limit $\lambda = \mu_0/\mu \ll 1$: $P_0 = O(\mu E)$

For flows to be of same size, and yield stagnation point, requires relation:

$$\ell_R = \sqrt{2\lambda}\ell_z \quad \text{since } \lambda \text{ is small, consistent w/ slender shape}$$

Estimate volume flux Q_0 through tendril, $Q_0 \sim U_z$ (Area)

$$Q_0 = c_0(E\ell_z)(\pi\ell_R^2) = c_0(16\pi\mu^2\mu_0E^4)/(\Delta\rho g)^3$$

$\leftarrow O(1)$ constant to be determined

Note: similar arguments can be made for entrainment of 2D sheets

Long-Wavelength Model for Tendril

A more precise analysis of the tendril dynamics yields

$$Q_0 = (Ez)\pi R^2(z) - \frac{\pi R^4(z)}{8\mu_0} \left(\frac{dP_0}{dz} + \Delta\rho g \right), \quad P_0 = 2\mu E \left(1 + \frac{z}{R(z)} \frac{dR}{dz} \right)$$

comprising a 2nd order non-linear ODE for radius $R(z)$.

Asymptotic limits are: $R_\infty(z) = \sqrt{Q_0(c_0)/(\pi Ez)}$ as $z \rightarrow \infty$

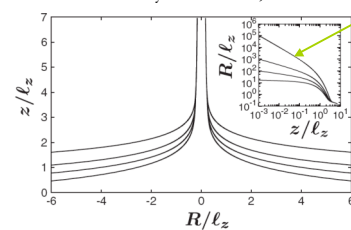
$$R_1(z) = B \left(\frac{\ell_z}{z} \right)^\alpha e^{-z/\ell_z} \quad \text{as } z \rightarrow 0$$

allows any power law form with exponent α , and coefficient B , characterizing the width and slope of the tendril near the base.

Continuous Family of Steady-State Shapes

Check above asymptotics by numerical integration of ODE for $R(z)$ for fixed Q_0 .

Find continuous family of solutions, with different upstream ($z \rightarrow 0$) power laws.



degenerate

Must use another piece of information – the exact large-scale interface deflection – to find a unique solution.

Shape of Deflected Interface

Make specific choice for interface deflection by placing point force, F , at a height S above origin. Straining flow generated, as required, with $E = F/2\pi\mu S^2$.

Solve for deflection by General Reciprocal Theorem (\sim method of images, Lee et al *JFM* '79) & normal stress balance (**visc. stress** \sim **gravity**)

$$R_I(z) = S\sqrt{(3\ell_z/2z)^{2/5} - 1}$$

Exactly how the interface levels out depends on the geometry of the driving global flow (could use point sink, vortex ring, etc.)

The physical tendril solution is the one which **smoothly** joins the interface.

Only One Tendril Smoothly Joins Interface

Vary c_0 (vary Q_0) and find only one tendril solution can smoothly join $R_I(z)$

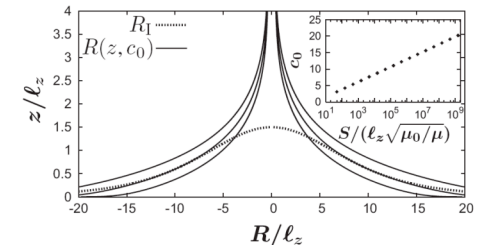


FIG. 4. Rescaled tendril solutions $R(z)$ for $c_0 = 3.4, 3.1$, and 2.9 (solid lines, top to bottom), together with the large-scale deflection solution $R_I(z)$ (dotted line) for $S/\ell_z = 15$ and $\mu_0/\mu = 0.1$. Only $c_0 = 3.1$ allows the two shapes to merge smoothly. Inset shows c_0 increases logarithmically with $S/(\ell_z\sqrt{\mu_0/\mu})$.

However, details of geometry of global flow (here, point force) have very weak, logarithmic effect on volume flux.

$$Q_0 = \frac{16\pi\mu^2\mu_0E^4}{(\Delta\rho g)^3} \left[\gamma_1 \log\left(\frac{S}{\ell_z\sqrt{\mu_0/\mu}}\right) + \gamma_2 \right]$$

γ_1, γ_2 depend on choice of driving flow (here point force)

Conclusions

Tendril width is selected by competition between viscous stress and gravity

Volume flux is strongly dependent on E and linear with λ . These trends should be possible to see in experiments.

Volume flux is very weakly dependent on global details ($S, R_I(z)$), so expect entrainment in experiments to be insensitive to large-scale fluctuations.