

Conservation laws on networks

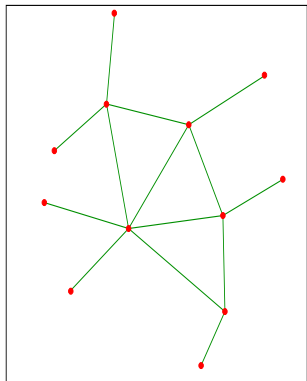
Mauro Garavello

University of Eastern Piedmont

joint works with R.M. Colombo and B. Piccoli

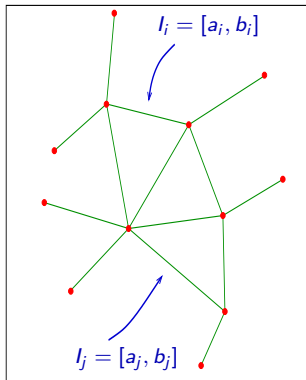
July 30, 2009

Conservation Laws on Networks



A network is a finite collection of
arcs and **vertices**

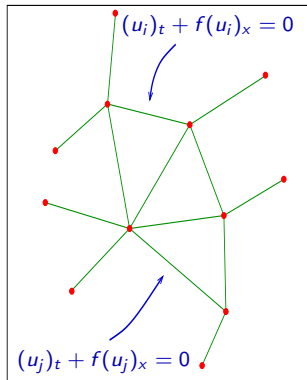
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Each arc is modeled by $I_i = [a_i, b_i]$

On each arc we consider the PDE
system $(u_i)_t + f(u_i)_x = 0$

Various applications



Car traffic

LWR model

$$\rho_t + (\rho v(\rho))_x = 0$$

- Coclite, G., Piccoli, *SIAM J. Math. Anal.* 36, 2005.
- Holden, Risebro, *SIAM J. Math. Anal.* 26, 1995.
- Lighthill, Whitham, *Proc. Roy. Soc. London Ser. A* 229, 1955.
- Richards, *Oper. Res.* 4, 1956.

Various applications



Car traffic

Aw-Rascle-Zhang model

$$\begin{cases} \rho_t + (\rho v)_x = 0, \\ (v + p(\rho))_t + v(v + p(\rho))_x = 0, \end{cases}$$

- Aw, Rascle, *SIAM J. Appl. Math.* 60, 2000.
- G., Piccoli, *Commun. Partial Differential Equations* 31, 2006.
- Zhang, *Transportation Research B* 36, 2002.

Various applications



Car traffic

Colombo phase transition model

Free flow

$$\left\{ \begin{array}{l} (\rho, q) \in \Omega_f, \\ \rho_t + [\rho \cdot v]_x = 0, \\ v = \left(1 - \frac{\rho}{R}\right) \cdot V, \end{array} \right.$$

Congested flow

$$\left\{ \begin{array}{l} (\rho, q) \in \Omega_c, \\ \rho_t + [\rho \cdot v]_x = 0, \\ q_t + [(q - Q) \cdot v]_x = 0, \\ v = \left(1 - \frac{\rho}{R}\right) \cdot \frac{q}{\rho}. \end{array} \right.$$

- Colombo, *SIAM J. Appl. Math.* 63, 2002.
- Colombo, Goatin, Piccoli, *J. Hyperbolic Differ. Equ.*, 2009.
- Colombo, Goatin, Priuli, *Nonlinear Anal.* 66, 2007.
- Goatin, *Math. Comput. Modelling* 44, 2006.

Various applications



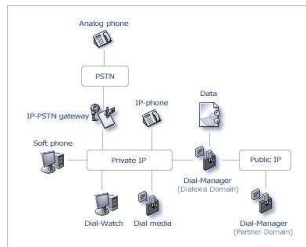
Gas pipelines

p -system

$$\begin{cases} \rho_t + q_x = 0, \\ q_t + \left(\frac{q^2}{\rho} + p(\rho) \right)_x = 0, \end{cases}$$

- Banda, Herty, Klar, *Netw. Heterog. Media* 1, 2006.
- Colombo, G., *SIAM J. Math. Anal.* 39, 2008.
- Colombo, Guerra, Herty, Sachers, *SIAM J. Control Optim.* 48, 2009.
- Colombo, Herty, Sachers, *SIAM J. Math. Anal.* 40, 2008.
- Colombo, Mauri, *J. Hyperbolic Diff. Eq.* 5, 2008.
- Colombo, Marcellini, *J. Mathematical Anal. and Appl.*

Various applications

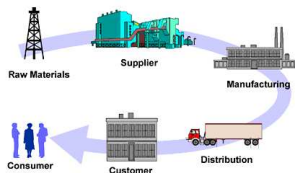


Data networks

$$\rho_t + f(\rho)_x = 0$$

- D'Apice, Manzo, Piccoli, *SIAM J. Appl. Math.* 68, 2008.

Various applications



Supply chains

$$\rho_t + (\min \{ \mu(t, x), v\rho \})_x = 0$$

- Armbruster, Degond, Ringhofer, *Bull. Inst. Math. Acad. Sin.* 2, 2007.
- Göttlich, Herty, Klar, *Commun. Math. Sci.* 4, 2006.
- D'Apice, Göttlich, Herty, Piccoli, *SIAM book series*, 2009.

Various applications



Blood circulation

$$\begin{cases} A_t + m_x = 0 \\ m_t + \left(\frac{\alpha m^2}{A} \right)_x + \frac{A}{\rho} p_x = -K \frac{m}{A} \end{cases}$$

- Čanić, Kim, *Math. Meth. Appl. Sci.* 26, 2003.
- Fernández, Milišić, Quarteroni, *Multiscale Model. Simul.* 4, 2005.

Various applications



Irrigation channel

De Saint-Venant equation

$$\begin{cases} H_t + (Hv)_x = 0 \\ v_t + \left(\frac{1}{2}v^2 + gH\right)_x = gS(H, v) \end{cases}$$

- Coron, d'Andréa-Novel, Bastin, ECC1999.
- Gugat, Leugering, *Ann. Inst. H. Poincaré Anal. Non Linéaire* 26, 2009.

The LWR model

$$\rho_t + f(\rho)_x = 0$$

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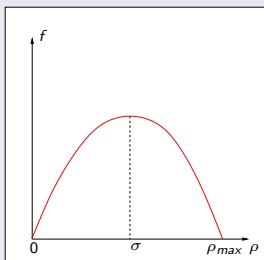
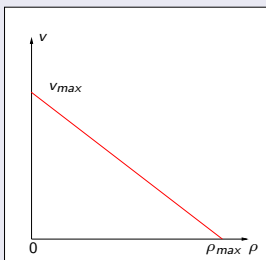
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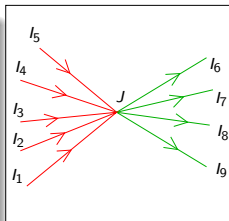
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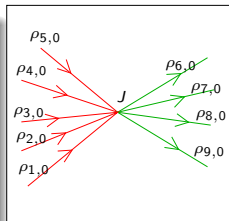
Solutions at nodes

- J node: n incoming arcs, m outgoing arcs



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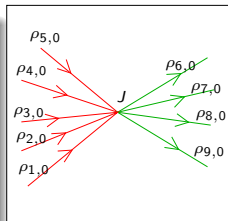
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Solutions at nodes

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- Consider an initial datum $\rho_{0,l}$ in each arc
- This corresponds to $n + m$ IBV problems

$$\begin{cases} (\rho_l)_t + f(\rho_l)_x = 0, & l \in \{1, \dots, n + m\} \\ \rho_l(0, x) = \rho_{l,0}(x), & x \in I_l, l \in \{1, \dots, n + m\} \\ \rho_l(t, 0) = ?, & t > 0, l \in \{1, \dots, n + m\} \end{cases}$$



Solutions at nodes ... the Riemann problem

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Definition

A **Riemann solver** at the node J is a function

$$\mathcal{RS} : [0, \rho_{max}]^{n+m} \rightarrow [0, \rho_{max}]^{n+m},$$

which gives the trace at the node of a solution to the corresponding Riemann problem.

The traces

- Given an arc of a node and an initial datum $\rho_{l,0}$, **not all** the elements in $[0, \rho_{max}]$ can be the trace at the node of a solution to a Riemann problem

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- We prescribe the conservation at J :

$$\sum_{i=1}^n f(\hat{\rho}_i) = \sum_{j=n+1}^{n+m} f(\hat{\rho}_j)$$

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- There are **infinitely many** Riemann solvers with these properties!

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Remark

If we “invert” the order of the last two rules, i.e. first we maximize the functional and then we impose some constraints, then we obtain a different Riemann solver.

Properties (P1), (P2) and (P3)

Property (P1)

\mathcal{RS} has the property (P1) if, given $(\rho_{1,0}, \dots, \rho_{n+m,0})$ and $(\rho'_{1,0}, \dots, \rho'_{n+m,0})$ such that $\rho_{l,0} = \rho'_{l,0}$ whenever $\rho_{l,0}$ or $\rho'_{l,0}$ is a bad datum, then

$$\mathcal{RS}(\rho_{1,0}, \dots, \rho_{n+m,0}) = \mathcal{RS}(\rho'_{1,0}, \dots, \rho'_{n+m,0}).$$

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The datum $\rho_{l,0}$ is called **bad** if

$$\rho_{l,0} < \sigma, \quad l \leq n \quad \text{or} \quad \rho_{l,0} > \sigma, \quad l \geq n+1$$

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i.e. $\rho_{l,0}$ gives a non trivial constraint for the flux solution at J

Properties (P1), (P2) and (P3)

\mathcal{RS} has the property (P2) if there exists $C \geq 1$ such that, for every equilibrium $(\rho_{1,0}, \dots, \rho_{n+m,0})$ for \mathcal{RS} and for every wave $(\rho_{l,0}, \rho_l)$ ($l \in \{1, \dots, n+m\}$) interacting with J at time \bar{t} , it holds

$$\text{Tot.Var.}_f(\bar{t}+) - \text{Tot.Var.}_f(\bar{t}-) \leq C \min \{ |f(\rho_{l,0}) - f(\rho_l)|, |\Gamma(\bar{t}+) - \Gamma(\bar{t}-)| \}.$$

- An equilibrium is a fixed point of \mathcal{RS}
- The functionals $\Gamma(t)$ and $\text{Tot.Var.}_f(t)$ are defined by

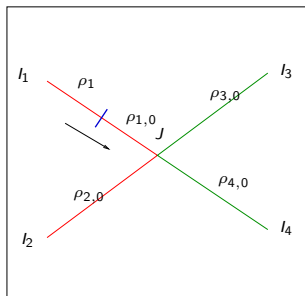
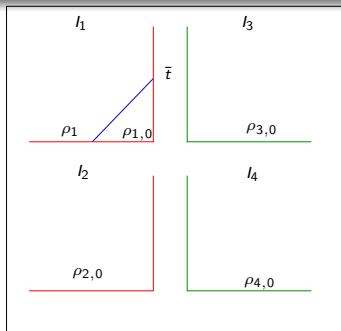
$$\Gamma(t) := \sum_{i=1}^n f(\rho_i(t, 0-))$$

$$\text{Tot.Var.}_f(t) := \sum_{l=1}^{n+m} \text{Tot.Var.}_f(\rho_l(t, \cdot))$$

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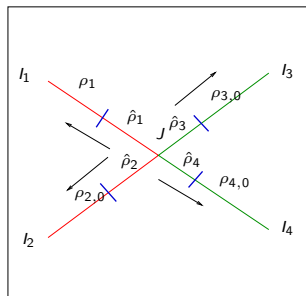
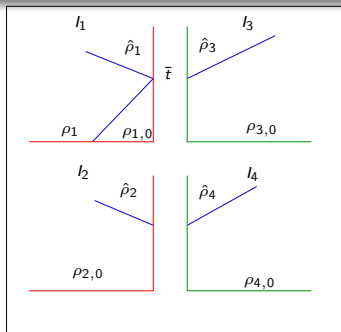
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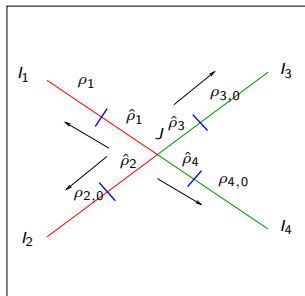
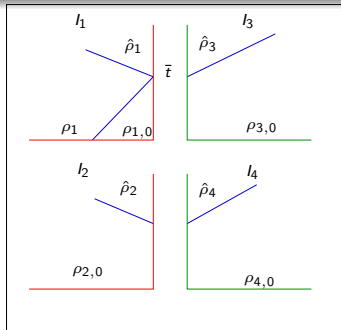
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$$|f(\rho_1) - f(\hat{\rho}_1)| + |f(\rho_{2,0}) - f(\hat{\rho}_2)| + |f(\rho_{3,0}) - f(\hat{\rho}_3)| + |f(\rho_{4,0}) - f(\hat{\rho}_4)| - |f(\rho_{1,0}) - f(\rho_1)| \leq C \min \{ |f(\rho_{1,0}) - f(\rho_1)|, |f(\hat{\rho}_1) + f(\hat{\rho}_2) - f(\rho_{1,0}) - f(\rho_{2,0})| \}.$$



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\mathcal{RS} satisfies the property (P3) if, for every equilibrium $(\rho_{1,0}, \dots, \rho_{n+m,0})$ of \mathcal{RS} and for every wave $(\rho_{l,0}, \rho_l)$ ($l \in \{1, \dots, n+m\}$) with $f(\rho_l) < f(\rho_{l,0})$, interacting with J at time $\bar{t} > 0$ it holds

$$\Gamma(\bar{t}+) \leq \Gamma(\bar{t}-).$$

Main result

Theorem [AIP 2009]

Let \mathcal{RS} be a Riemann solver satisfying properties (P1)–(P3). Fix initial conditions $\rho_{l,0} \in BV$.

For every $T > 0$, there exists a solution $(\rho_1, \dots, \rho_{n+m})$ to the Cauchy problem

$$\begin{cases} \frac{\partial}{\partial t} \rho_l + \frac{\partial}{\partial x} f(\rho_l) = 0 \\ \rho_l(0, x) = \rho_{l,0}(x) \end{cases} \quad l = 1, \dots, n+m$$

such that

$$\mathcal{RS}(\rho_1(t, 0), \dots, \rho_{n+m}(t, 0)) = (\rho_1(t, 0), \dots, \rho_{n+m}(t, 0))$$

for a.e. $t \in [0, T]$.

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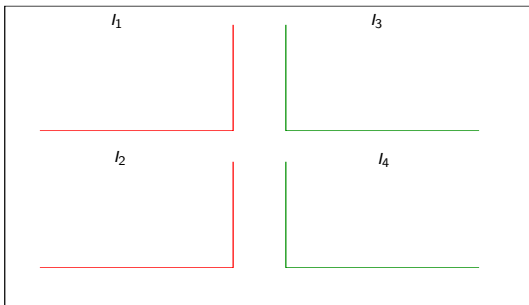
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Remark [JDE 2009]

The previous result holds also in the case of Riemann solvers \mathcal{RS} depending on time

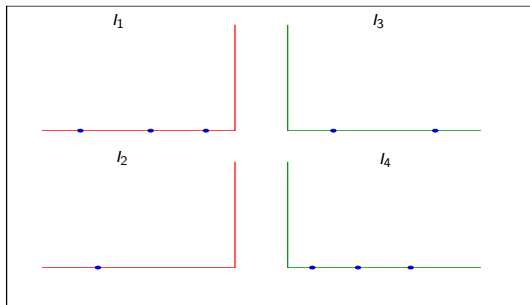
proof

- The proof is based on the **wave-front tracking** method



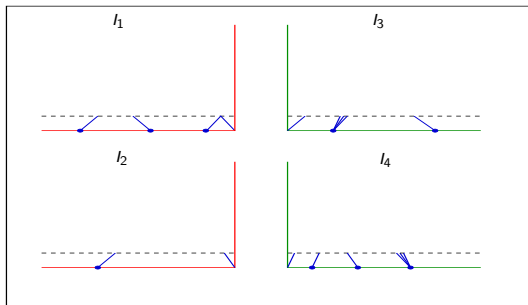
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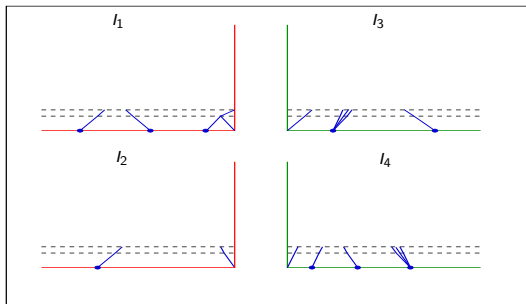
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- The proof is based on the **wave-front tracking** method
- We approximate the initial datum by p.c. functions
- We solve each Riemann problem until the first interaction happens



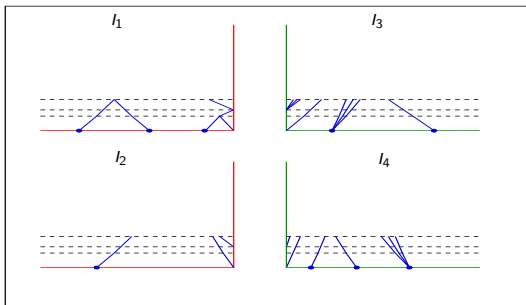
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- 3 In general, there is not a bound for the total variation of the density

Continuous dependence

Theorem [AIP 2009]

Fix a node J and a Riemann solver \mathcal{RS} satisfying (P1), (P2) and (P3) and such that

$$\text{Tot.Var.}_f(\bar{t}+) \leq \text{Tot.Var.}_f(\bar{t}-)$$

for every time \bar{t} at which an interaction of a wave with J happens. Then there exists a **unique** solution to the Cauchy problem and the solution depends in a **Lipschitz continuous** way on the initial datum with respect to the L^1 -topology.

Continuous dependence (idea of the proof)

- 1 Introduce a differential structure on L^1 .

[Bressan, Colombo, 1995] [Bressan, Crasta, Piccoli, 2000]

$\gamma : [0, 1] \rightarrow L^1$ a curve s.t. $\gamma(\theta)$ is a piecewise constant functions with N discontinuities: $x_1(\theta) < x_2(\theta) < \dots < x_N(\theta)$.

Tangent vector $\dot{\gamma}(\theta) = (v, \xi)(\theta) \in L^1 \times \mathbb{R}^N$ if

$$L^1 \ni v(\theta, x) \doteq \lim_{h \rightarrow 0} \frac{\gamma(\theta + h, x) - \gamma(\theta, x)}{h}, \quad \text{for a.e. } x,$$

$$\xi_i(\theta) \doteq \lim_{h \rightarrow 0} \frac{x_i(\theta + h) - x_i(\theta)}{h}, \quad i = 1, \dots, N.$$

The norm of $(v, \xi)(\theta)$ is defined by:

$$\|(v, \xi)(\theta)\| = \|v(\theta)\|_{L^1} + \sum_{i=1}^N |\xi_i(\theta)| |\gamma(\theta, x_i+) - \gamma(\theta, x_i-)|.$$

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- 2 Define a distance between piecewise constant functions

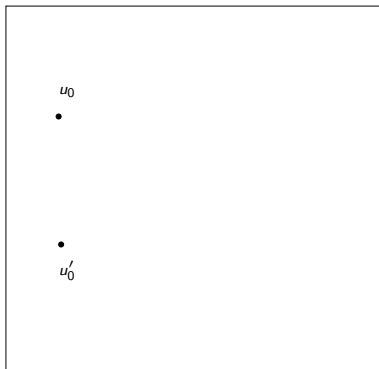
$$d(u, u') = \inf \int_0^1 \|\dot{\gamma}(t)\|$$

$$d(u, u') \sim \|u - u'\|_{L^1}$$

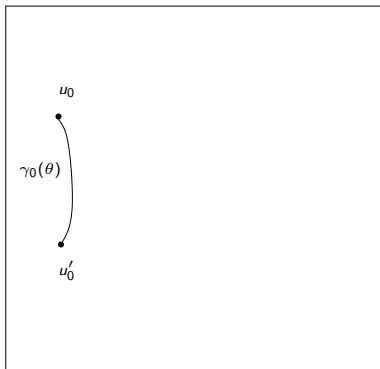
Continuous dependence (idea of the proof)

- 1 Introduce a differential structure on L^1 .
- 2 Define a distance between piecewise constant functions
- 3 Prove that the norm of tangent vectors are not increasing in time along wave front tracking solutions

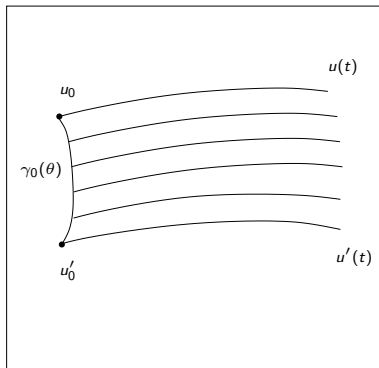
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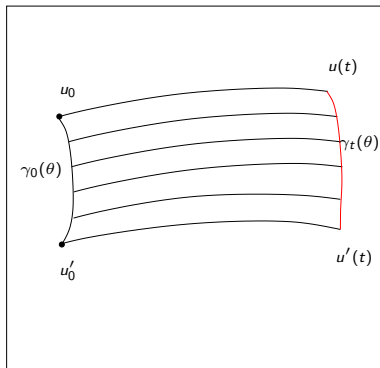
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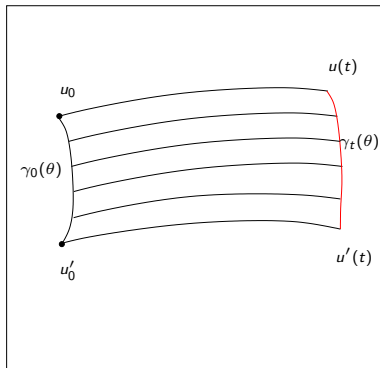
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Continuous dependence (idea of the proof)



For a.e. θ , the norm $\|\dot{\gamma}_s(\theta)\|$ is not increasing with respect to s .

The p -system in a tube

$$\begin{cases} \partial_t \rho + \partial_x q = 0 \\ \partial_t q + \partial_x \left(\frac{q^2}{\rho} + p(\rho) \right) = 0 \end{cases}$$

- $\rho(t, x)$ **density** of the fluid

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- $p(\rho)$ **pressure law**

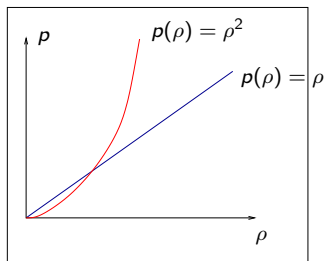
The pressure law p

$$p \in C^2(]0, +\infty[;]0, +\infty[)$$

$$p' > 0$$

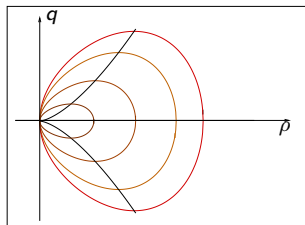
$$p'' \geq 0$$

Typical case: $p(\rho) = k\rho^\gamma$ $\gamma \geq 1$



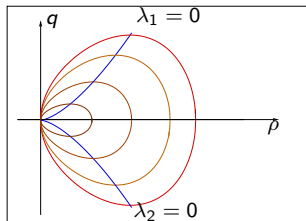
Lax curves and other quantities

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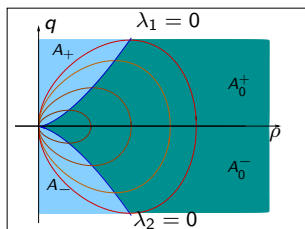
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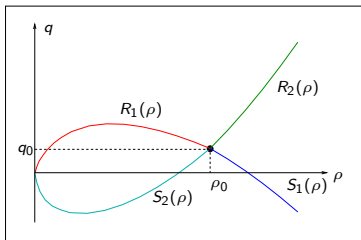
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(E): $\sum \|\nu_l\| F(\rho_l(t, 0), q_l(t, 0)) \leq 0$ (entropy inequality)

$$E(\rho, q) = \frac{q^2}{2\rho} + \rho \int_{\rho_*}^{\rho} \frac{p(r)}{r^2} dr$$

$$F(\rho, q) = \frac{q}{\rho} \cdot (E(\rho, q) + p(\rho))$$

$$\|\nu_l\| = \text{section of the } l\text{-th tube}$$

Stability of solutions for Riemann problems

Theorem [NHM 2006]

Fix n initial states $(\hat{\rho}_l, \hat{q}_l) \in \mathring{A}_0$ satisfying

$$\begin{cases} \sum \|\nu_l\| \hat{q}_l = 0, \\ P(\hat{\rho}_l, \hat{q}_l) = P_* \quad l = 1, \dots, n \\ \sum \|\nu_l\| F(\hat{\rho}_l, \hat{q}_l) < 0. \end{cases}$$

Then, for every initial datum closed to $(\hat{\rho}_l, \hat{q}_l)$, there exists (locally) a unique solution (ρ_l, q_l) to the Riemann problem.

The proof is based on the Implicit Function Theorem

The Cauchy problem

Theorem [SIMA 2008]

Fix n subsonic states $(\hat{\rho}_l, \hat{q}_l) \in (\mathring{A}_0)$ such that

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Then, there exists a map $S: [0, +\infty[\times \mathcal{D} \mapsto \mathcal{D}$, with the properties:

- $\mathcal{D} \supseteq \{(\rho, q) \in L^1(\mathbb{R}^+; \mathbb{R}^+ \times \mathbb{R})^n : \text{Tot.Var.}(\rho, q) \leq \delta_0\}$;

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- the map $t \mapsto S_t(\rho, q)$ is a weak entropy solution to the Cauchy Problem.

The Cauchy problem

Interaction estimate at the junction

For any 1-waves σ_l^- hitting the junction and producing the 2-waves σ_l^+ , it holds

$$\sum_{l=1}^n |\sigma_l^+| \leq K_J \cdot \sum_{l=1}^n |\sigma_l^-|.$$

The Cauchy problem

Glimm functional

$$V(t) = \sum_{l=1}^n \sum_{\alpha \in \mathcal{J}_l} [2K_J \cdot |\sigma_{l,1,\alpha}| + |\sigma_{l,2,\alpha}| + |\sigma_{l,3,\alpha}|]$$

$$Q(t) = \sum_{l=1}^n \sum \{ |\sigma_{l,i,\alpha} \sigma_{l,j,\beta}| : (\sigma_{l,i,\alpha}, \sigma_{l,j,\beta}) \in \mathcal{A}_l \}$$

$$\Upsilon(t) = V(t) + K_1 \cdot Q(t),$$

The Cauchy problem

Liu-Yang functional

$$\Phi(u_1, u_2) = \sum_{l=1}^n \sum_{i=1}^2 \int_0^{+\infty} |s_{l,i}(x)| W_{l,i}(x) dx,$$

$$W_{l,i}(x) = 1 + \kappa_1 A_{l,i}(x) + \kappa_1 \kappa_2 [\Upsilon(u_1) + \Upsilon(u_2)].$$

- Liu-Yang, Comm. Pure Appl. Math. 52, 1999.
- Bressan-Liu-Yang, Ration. Mech. Anal. 149, 1999.