



Entropy, Inference, and Channel Capacity

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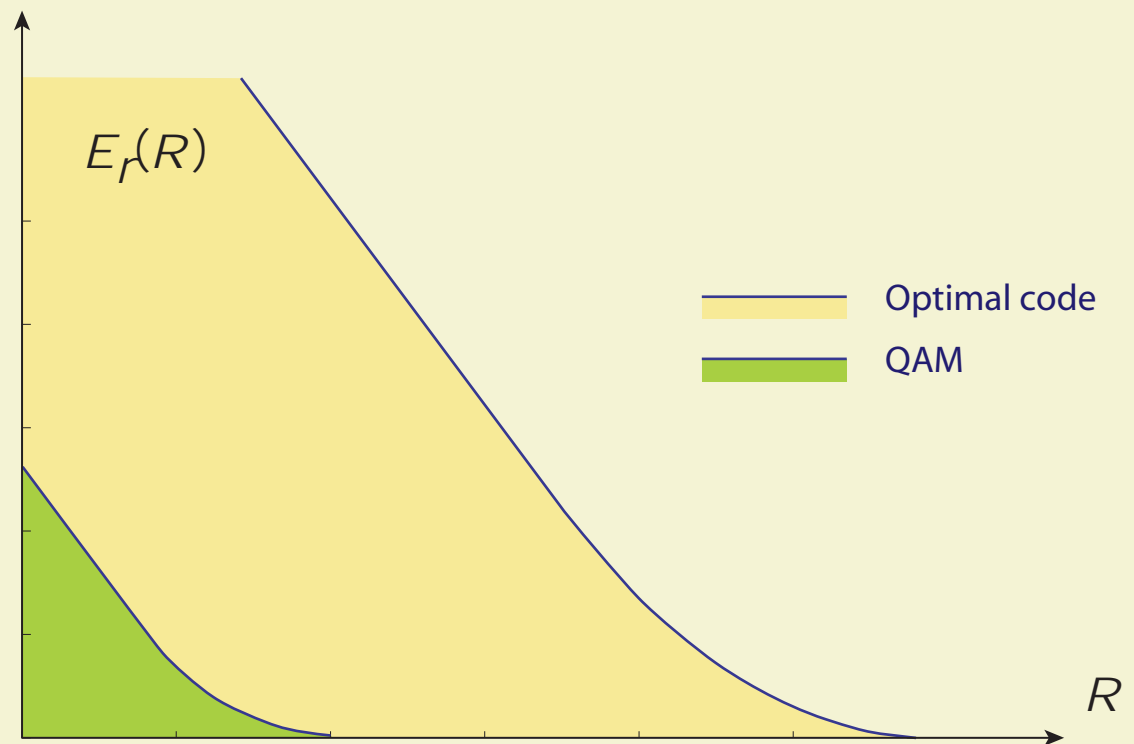
Overview

Hypothesis testing and channel coding

Structure of optimal codes

Error exponents

Algorithms



Outline (today)

Introduction

Relative entropy & Large deviations

Hypothesis testing

Channel capacity

Conclusions

Memoryless Channel Model

Memoryless channel with input sequence X , output sequence Y

Channel kernel $P(dy / x) = P\{Y_t = dx / X_t = x\}$

If X is i.i.d. with marginal distribution μ

Then, Y is i.i.d. with marginal distribution

$$(\cdot) = \int P(\cdot / x) \mu(dx)$$

Random codebook

Channel kernel $P(dy / x) = P\{Y_t \in dx / X_t = x\}$

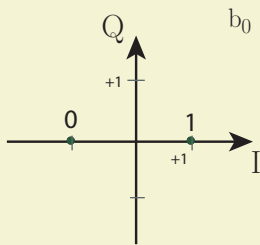
N -dimensional code words $X^i, \quad i = 1, 2, \dots, e^{NR}$

N -dimensional output Y received: i.i.d.,
with marginal distribution

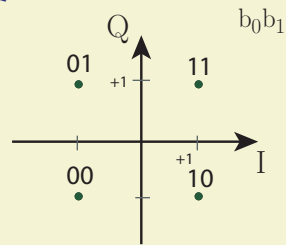
IEEE Std 802.11a-1999

SUPPLEMENT TO IEEE STANDARD FOR INFORMATION TECHNOLOGY

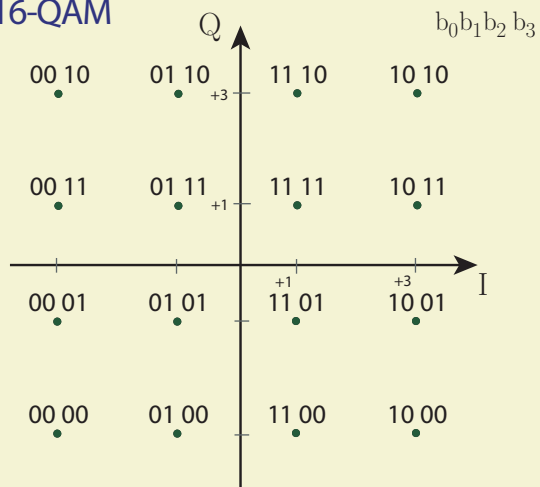
BPSK



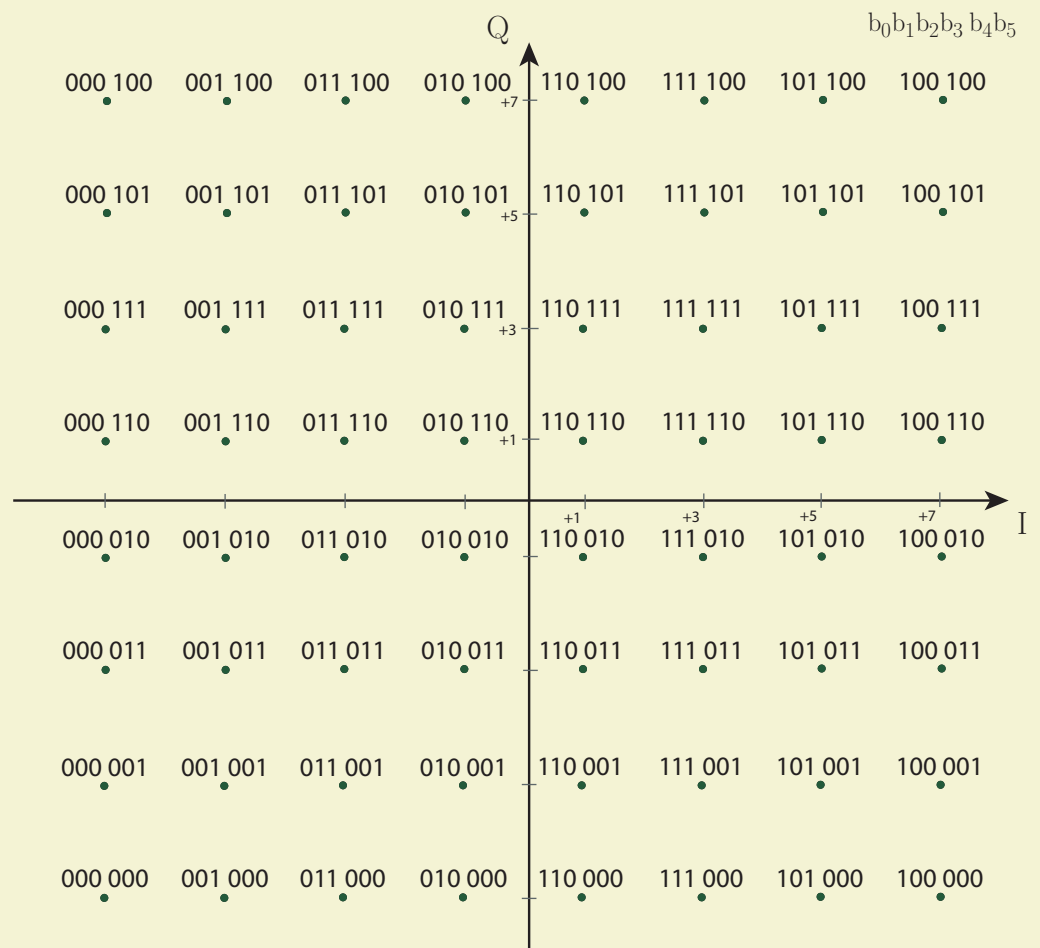
QPSK



16-QAM



64-QAM



Questions & Objectives

1. What is the structure of optimal μ ?
2. Construct algorithms based on this structure
3. Worst-case modeling to *simplify* code construction
4. Decoding algorithms and evaluation

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1. What is the structure of optimal μ ?
2. Construct algorithms based on this structure
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Methodology & Viewpoint:

Hypothesis testing

Large deviations

Convex & linear optimization theory

Example: Rayleigh Channel $Y = AX + N$

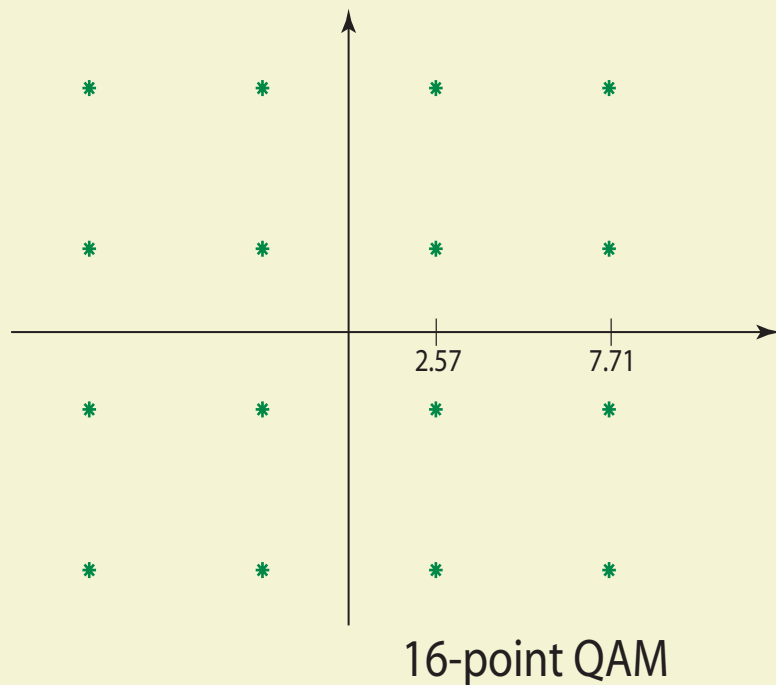
A and N are *i.i.d.* and mutually independent:

$$\frac{\sigma_A^2}{\sigma_X^2} = 1, \quad \frac{\sigma_N^2}{\sigma_X^2} = 1, \quad \text{and} \quad \frac{\sigma_Y^2}{\sigma_X^2} = 26.4 \quad (\text{SNR}=14.2 \text{ dB})$$

Example: Rayleigh Channel $Y = AX + N$

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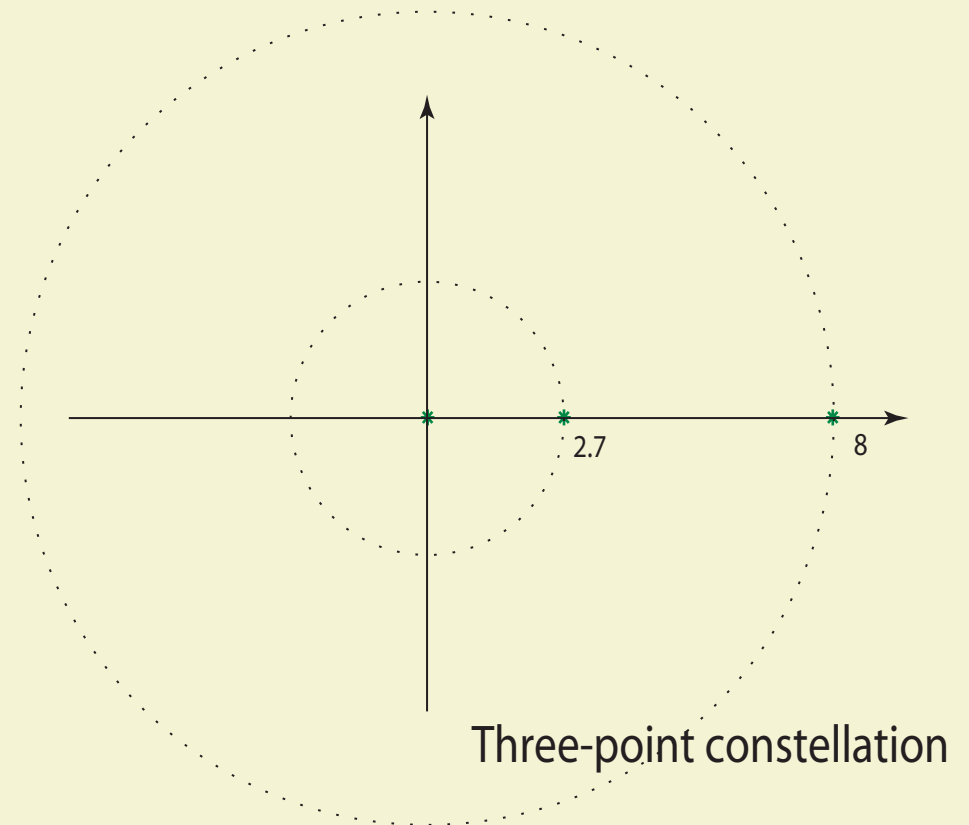
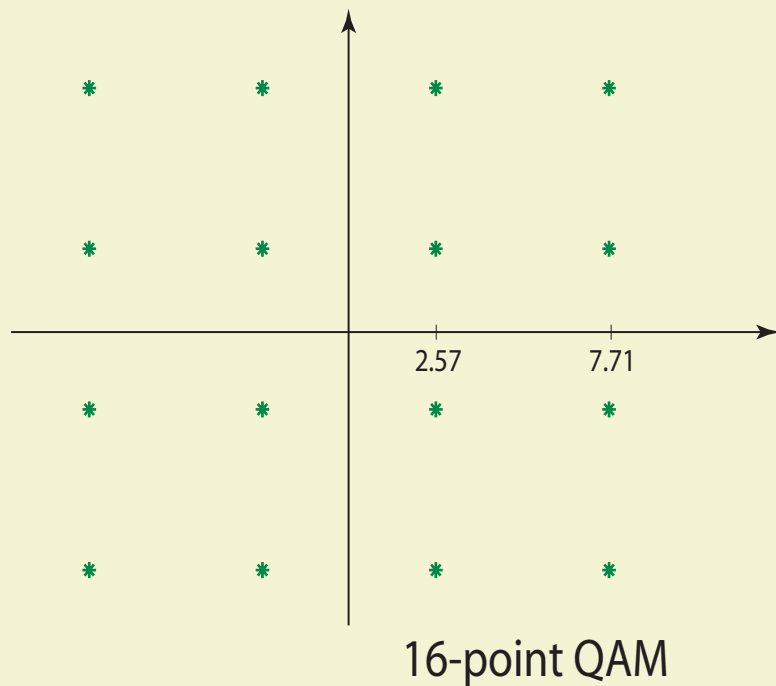
Standard: 16-point QAM

Rate: $I = 0.2$ nats/symbol.

Example: Rayleigh Channel $Y = AX + N$

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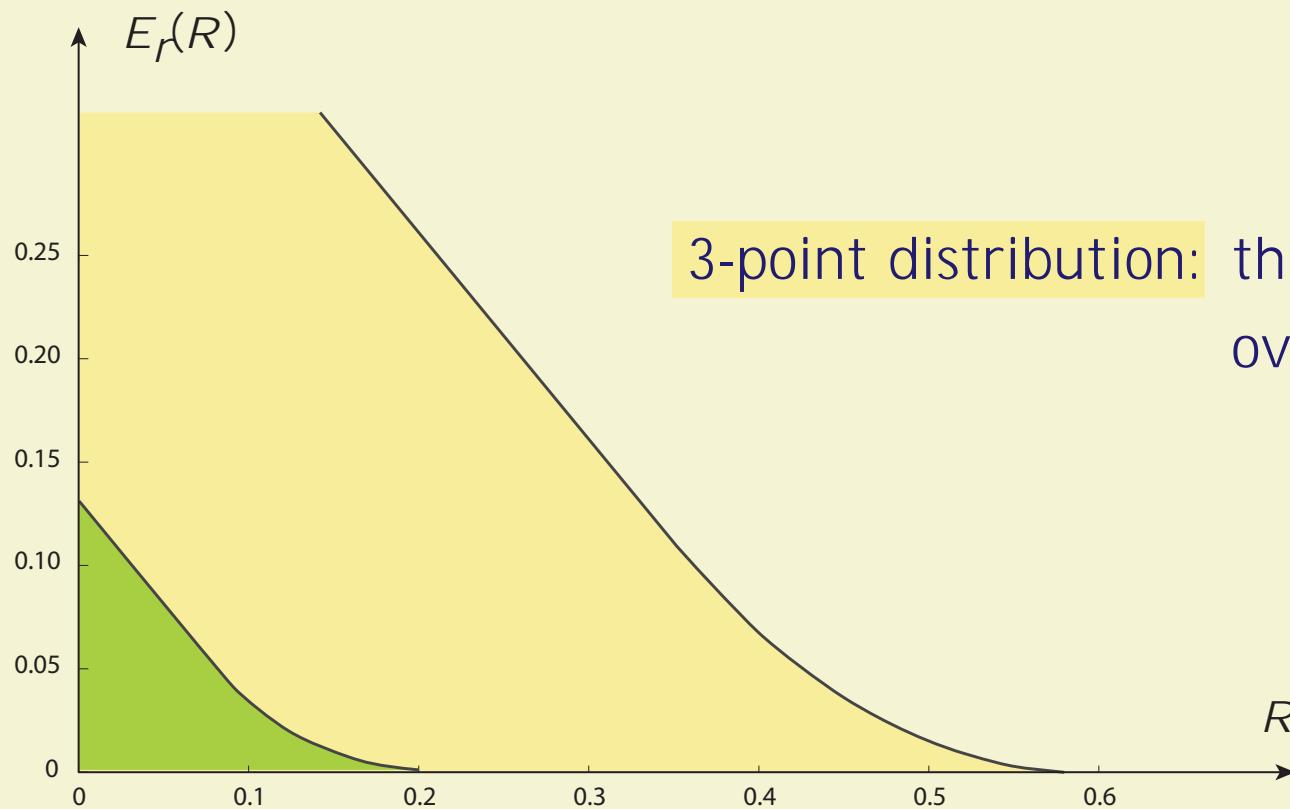
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Example: Rayleigh Channel $Y = AX + N$

A and N are *i.i.d.* and mutually independent:

$$\frac{\sigma_A^2}{A} = 1, \quad \frac{\sigma_N^2}{N} = 1, \quad \text{and} \quad \frac{\sigma_P}{P} = 26.4 \quad (\text{SNR}=14.2 \text{ dB})$$



3-point distribution: three-fold improvement over 16-point QAM

Outline

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Relative entropy & Large deviations

Hypothesis testing

Channel capacity

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Large Deviations

$\mathbf{X} = \{X_1, X_2, \dots\}$ a nice Markov chain on X , marginal distribution μ

Simulate a function $g: X \rightarrow \mathbb{R}$

$$\hat{c}_n = n^{-1} \sum_{t=1}^n g(X_t)$$

Large Deviations

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Simulate a function $g: X \rightarrow \mathbb{R}$

$$\hat{c}_n = n^{-1} \sum_{t=1}^n g(X_t) \quad c_0 = \mu(g)$$

Probability of over-estimate $c > c_0$

$$n^{-1} \log P \left(n^{-1} \sum_{t=1}^n g(X_t) > c \right) \sim -n I(c)$$

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$$n^{-1} \log P \left(n^{-1} \sum_{t=1}^n g(X_t) > c \right) \sim -I(c)$$

Rate function & log-moment generating function

$$I(c) = \sup_{\lambda > 0} [\lambda c - \Lambda(\lambda)] \quad \Lambda(\lambda) = \lim_n n^{-1} \log E \exp \left(\sum_{t=1}^n \lambda g(X_t) \right)$$

Hoeffding's Bound

$\mathbf{X} = \{X_1, X_2, \dots\}$ is i.i.d. on $X = [0, 1]$ $g(x) = x$

Marginal distribution μ unknown

$$\hat{c}_n = n^{-1} \sum_{t=1}^n X_t \quad c_0 = \mu(g)$$

Worst-case rate function & log-moment generating function

$$\inf \{ \mu(c) : \mu(g) = c_0 \} \quad \sup \{ \mu(\cdot) : \mu(g) = c_0 \}$$

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$$\inf \{ \mu(c) : \mu(g) = c_0 \} \quad \sup \{ \mu(\cdot) : \mu(g) = c_0 \}$$

Solution: μ is binary on $\{0, 1\}$

Bennett's Lemma

$\mathbf{X} = \{X_1, X_2, \dots\}$ is i.i.d. on $X = [0, 1]$ Mean *and* variance given

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Worst-case rate function & log-moment generating function

$$\inf \{ \mu(c) : \mu(g_i) = c_i, i = 1, 2 \} \quad \sup \{ \mu(\cdot) : \mu(g_i) = c_i, i = 1, 2 \}$$

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Generalized Bennett's Lemma

$\mathbf{X} = \{X_1, X_2, \dots\}$ is i.i.d. on $X = [0, 1]$ n moments g_i given

Marginal distribution μ unknown

$$\hat{c}_n = n^{-1} \sum_{t=1}^n g(X_t)$$

Worst-case moment generating function: $(\cdot) = E[e^{g(X_t)}] = \mu, e^g$

Generalized Bennett's Lemma

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Worst-case moment generating function: $(\cdot) = E[e^{g(X_t)}] = \mu, e^g$

Linear program over \mathcal{M} :

$$\begin{aligned} \max \quad & \mu, e^g \\ \text{s. t.} \quad & \mu, g_i = c_i, \quad i = 1, \dots, n. \end{aligned}$$

μ is discrete

Sanov's Theorem

State space: X Probability measures: M

Notation: $\mu, g = \mu(g) := \int g(y) \mu(dy)$ μ a measure
 g a function on X

Empirical measures:

$$L_n := \frac{1}{n} \sum_{t=0}^{n-1} \delta_{X_t} \quad L_n \in M \text{ for } n \geq 1$$

$$L_n, g = \frac{1}{n} \sum_{t=0}^{n-1} g(X_t)$$

Sanov's Theorem

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Relative entropy:

$$D(\mu \parallel \nu) = \int \log \frac{d\mu}{d\nu} = \int \log \frac{d\mu}{d\nu} (dx)$$

Sanov's Theorem

Law of large numbers:

$$L_n := \frac{1}{n} \sum_{t=0}^{n-1} x_t$$

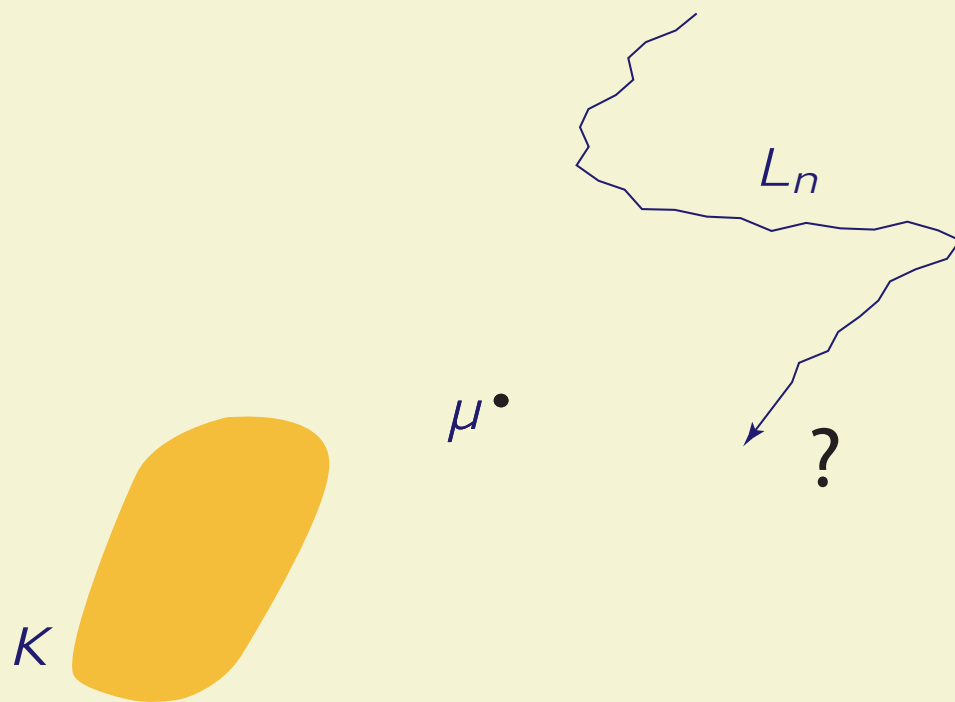
$$L_n \rightarrow \mu, \quad n \rightarrow \infty$$



Sanov's Theorem

Convex set of probability measures $K \subset M$ $\mu \in K$

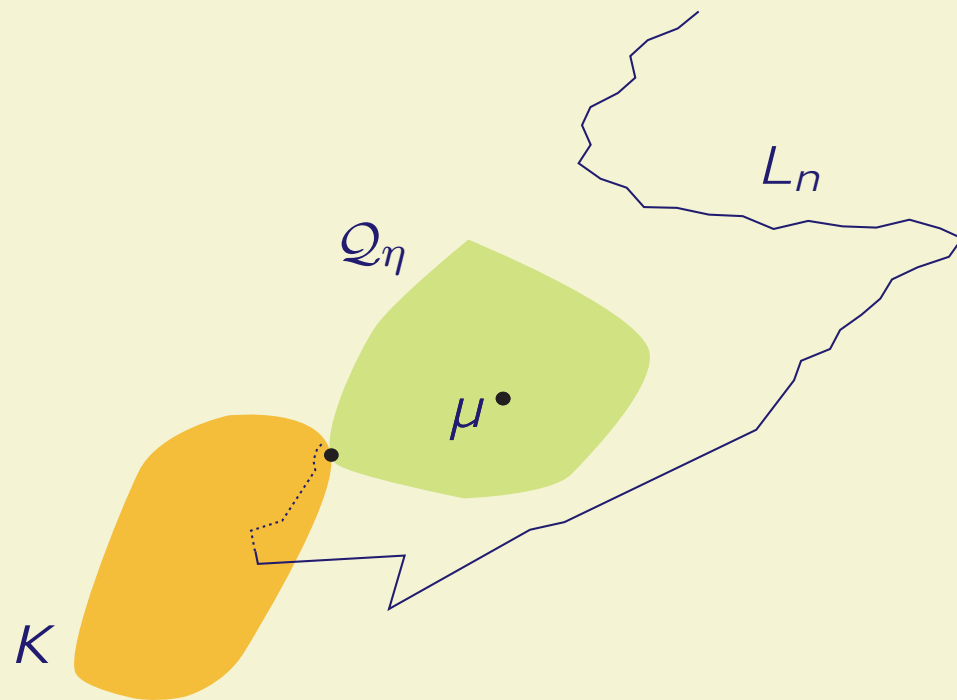
$$n^{-1} \log P\{L_n \in K\} \rightarrow -I(\mu \parallel \nu)$$



Sanov's Theorem

Convex set of probability measures $K \subset M$, $\mu \in K$

$$n^{-1} \log P\{L_n \in K\} \sim -\eta = -\inf_K J(\cdot)$$

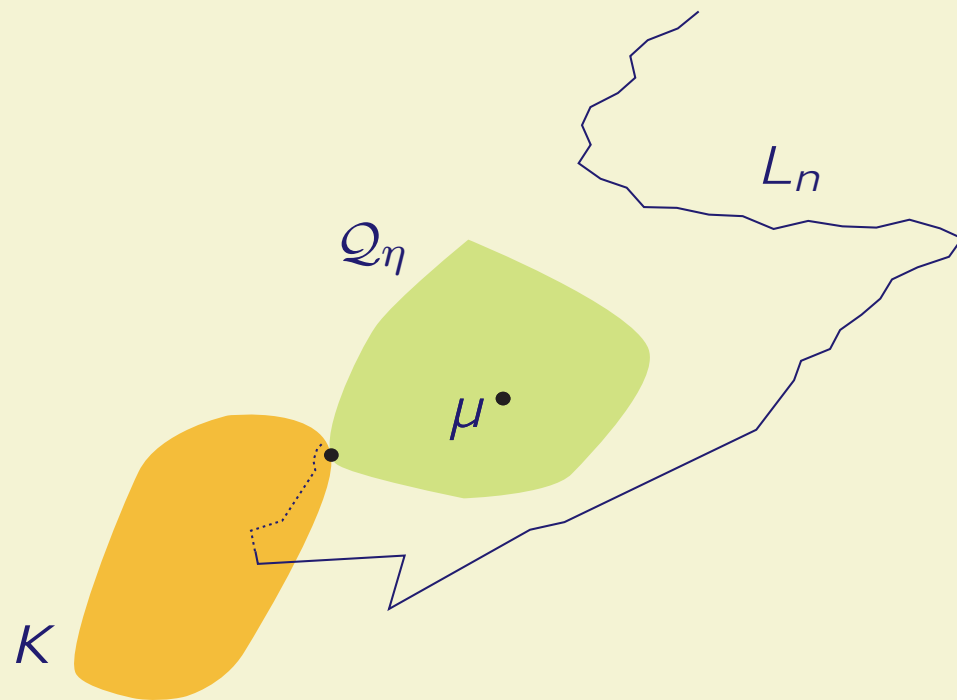


$$Q_\eta = \{ \mu : J(\mu) < \eta \}$$

Sanov's Theorem

i.i.d. source: $J(\cdot) = D(\cdot \parallel \mu)$

Markov: $J(\cdot) = \inf D(\tilde{P} \parallel P) : \tilde{P} \text{ tr. kernel with } \cdot \text{ invariant}$



$$Q_\eta = \{ \cdot : J(\cdot) < \eta \}$$

Sanov's Theorem

Example: $K = \{ : , g \ c \}$

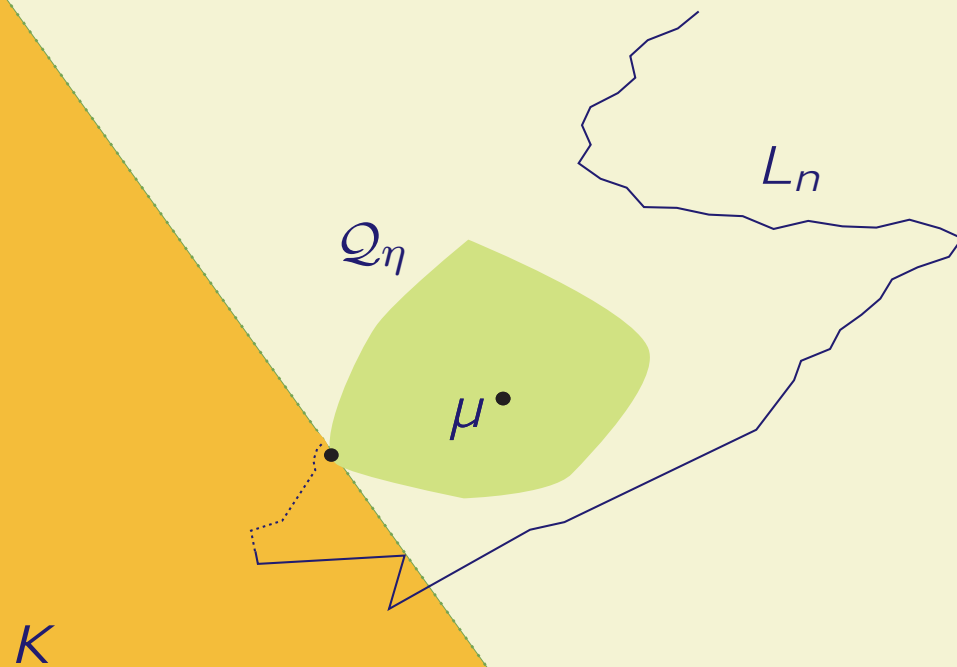
$$n^{-1} \log P\{L_n \in K\} - \eta = - \inf_{, g \ c} J(\) = - \quad (c)$$

Sanov's Theorem

Example: $K = \{ : ,g \leq c \}$

$$n^{-1} \log P\{L_n \in K\} \approx -\eta = - \inf_{,g \leq c} J() = - (c)$$

$,g \leq c$



$$Q_\eta = \{ : J() < \eta \}$$

Outline

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Neyman Pearson Hypothesis Testing

Observations $\mathbf{X} = \{X_t : t = 1, 2, \dots, N\}$

X i.i.d. with marginal π_j under H_j , $j = 0, 1$

Hypothesis test:

$$\phi(x) = 1 \text{ if } x \in A_1 \subset \mathcal{A}^N$$

Error Probabilities

$$P_{e,0} = P_0 \{\phi(X) = 1\}, \quad P_{e,1} = P_1 \{\phi(X) = 0\}$$

$$\text{N-P Criterion: } \inf_{\phi} P_{e,1} \text{ subject to } P_{e,0} \leq e^{-N}$$

Neyman Pearson Hypothesis Testing

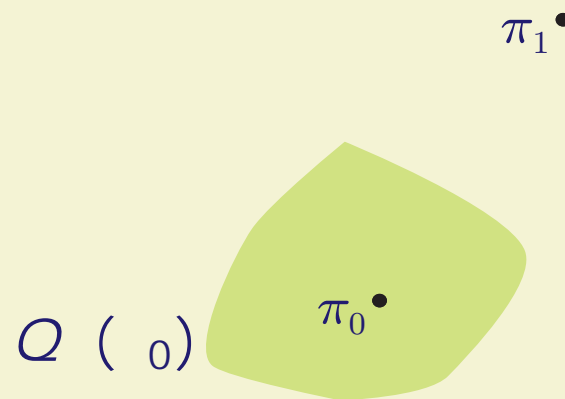
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Error Probabilities

$$P_{e,0} = P_0 \{\phi(\mathbf{X}) = 1\}, \quad P_{e,1} = P_1 \{\phi(\mathbf{X}) = 0\}$$

Solution: $\phi(\mathbf{X}) = 0$ if $L_n \geq Q(\alpha)$



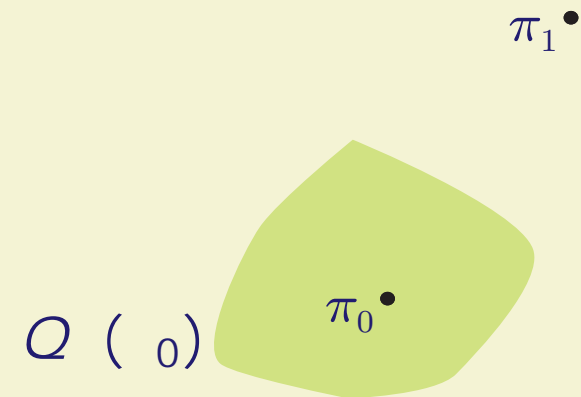
N-P Criterion: $\inf_{\phi} P_{e,1}$ subject to $P_{e,0} \leq \alpha$

Neyman Pearson Hypothesis Testing

Solution: $\phi(X) = 0$ if $L_n \leq Q(\alpha)$

$$\lim_N N^{-1} \log P_0\{N = 1\} = -$$

$$\lim_N N^{-1} \log P_1\{N = 0\} = -$$



Neyman Pearson Hypothesis Testing

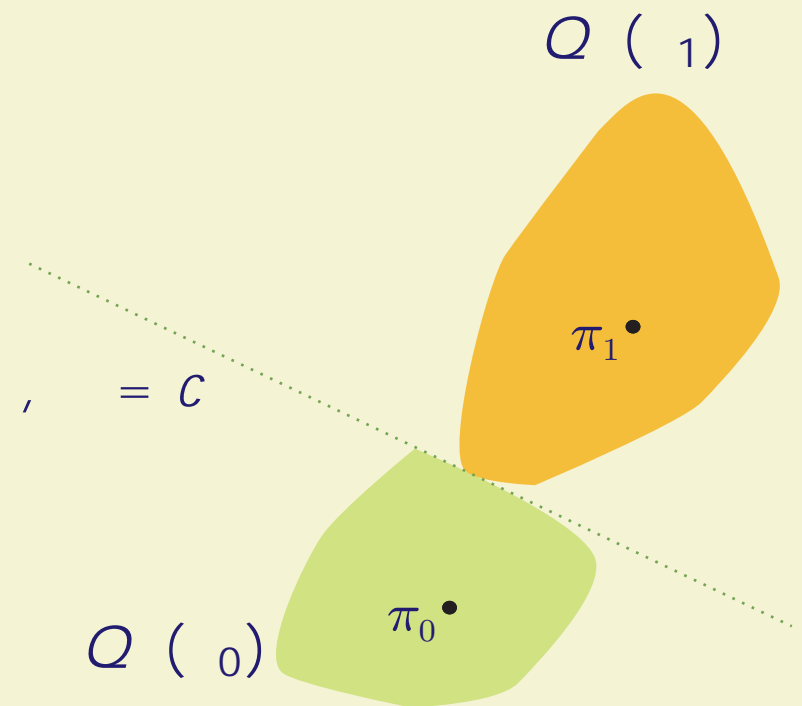
Solution: $\phi(X) = 0$ if $L_n \leq Q(\alpha)$

$$\lim_N N^{-1} \log P_0\{N = 1\} = -$$

$$\lim_N N^{-1} \log P_1\{N = 0\} = -$$

$$= \inf \{J_1(\alpha) : J_0(\alpha) \leq \alpha\}$$

$$= \inf \{ \alpha > 0 : Q(\alpha) \leq Q(\alpha) = \alpha \}$$



Robust Neyman Pearson Hypothesis Testing

Uncertainty classes defined by moment constraints

$$\pi_0 \in \mathbb{P}_0$$

$$\pi_1 \in \mathbb{P}_1$$

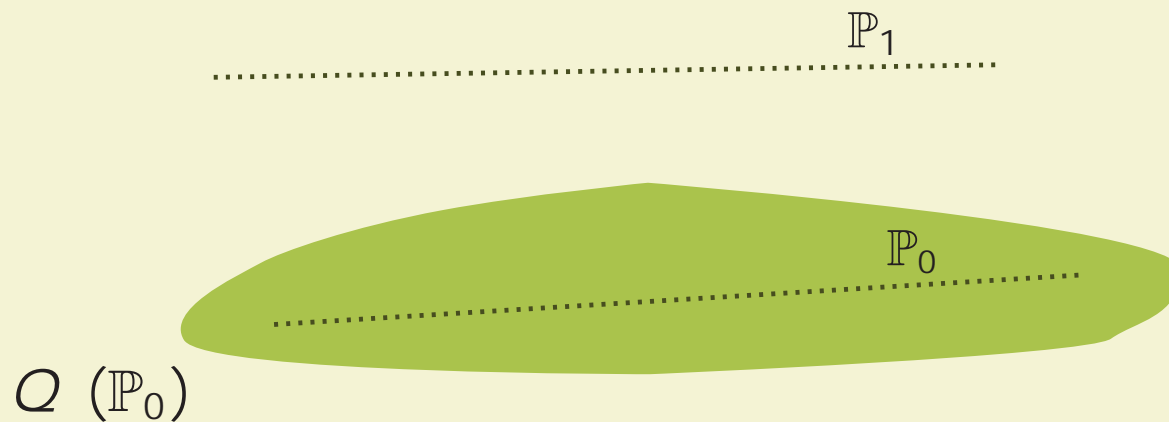


Robust Neyman Pearson Hypothesis Testing

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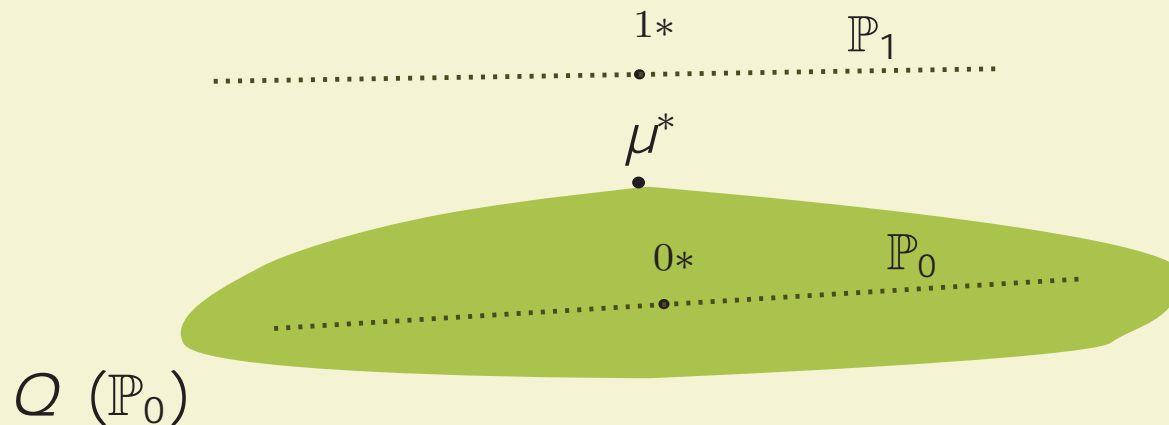


Robust Neyman Pearson Hypothesis Testing

Uncertainty classes defined by moment constraints

There exist $\pi_0^* \in \mathbb{P}_0, \pi_1^* \in \mathbb{P}_1$, and μ^* solving,

$$\beta^* = \inf_{\pi_1 \in \mathbb{P}_1} \inf_{\mu \in \mathcal{Q}_\eta(\mathbb{P}_0)} D(\mu \parallel \pi_1)$$

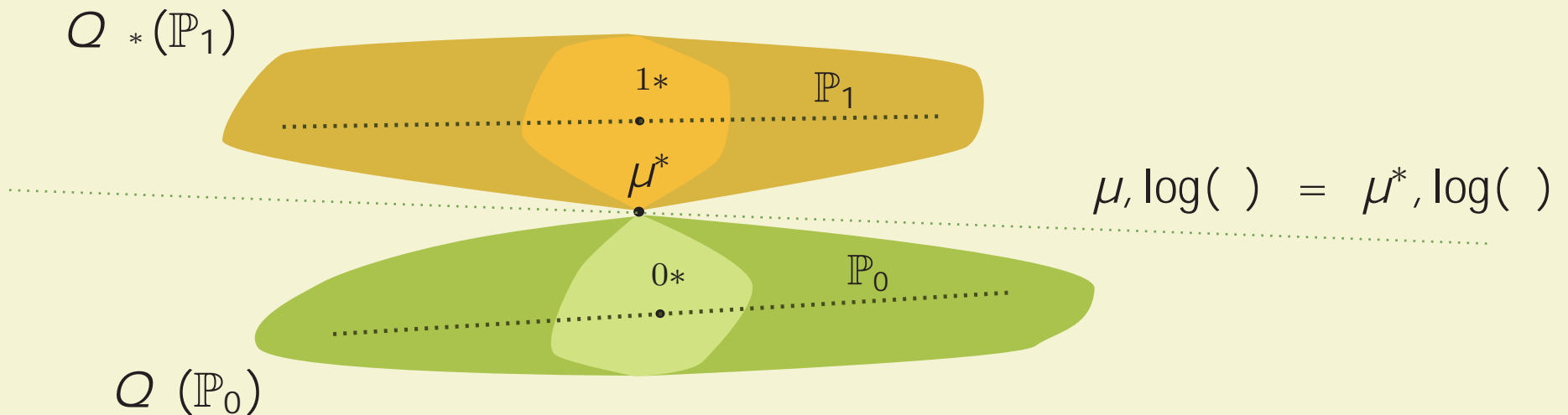


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Optimizers again *discrete*

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Channel Coding and Sanov's Theorem

Channel kernel $P(dy / x) = P\{Y_t = dx / X_t = x\}$

N -dimensional code words $X^i, \quad i = 1, 2, \dots, e^{NR}$

N -dimensional output Y received

X is i.i.d. with marginal distribution μ

Y is i.i.d. with marginal distribution

$$(\cdot) = \int P(\cdot / x) \mu(dx)$$

Channel Coding and Sanov's Theorem

Channel kernel $P(dy / x) = P\{Y_t \in dx / X_t = x\}$

N -dimensional code words $X^i, \quad i = 1, 2, \dots, e^{NR}$

N -dimensional output Y received

If i is the true codeword then
 (X^i, Y) has marginal distribution

$$\mu \int P(dx, dy) = \mu(dx) P(x, dy)$$

Otherwise, independence:

$$\mu \int (dx, dy) = \mu(dx) \int (dy)$$

Channel Coding and Sanov's Theorem

Two hypotheses based on observations:

$$H_0: \mu(dx, dy) = \mu(dx) \nu(dy)$$

$$H_1: \mu \ll P(dx, dy) = \mu(dx) P(x, dy)$$

$\mu \ll P$

μ

Channel Coding and Sanov's Theorem

Two hypotheses based on observations:

$$H_0: \mu(dx, dy) = \mu(dx) \nu(dy)$$

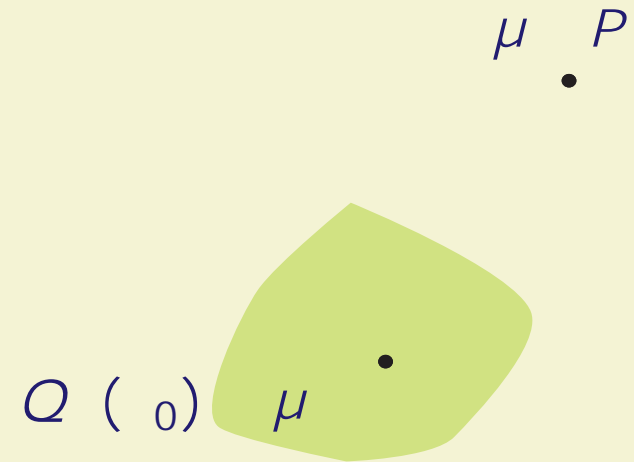
$$H_1: \mu(dx, dy) = \mu(dx) P(x, dy)$$

Solution: Reject codeword i ($\phi = 0$)

$$\text{if } L_n \leq Q(\epsilon)$$

Empirical distributions for
joint observations

$$(X^n, Y^n)$$



Channel Coding and Sanov's Theorem

Solution: $\phi = 0$ if $L_n \rightarrow Q(\mu)$

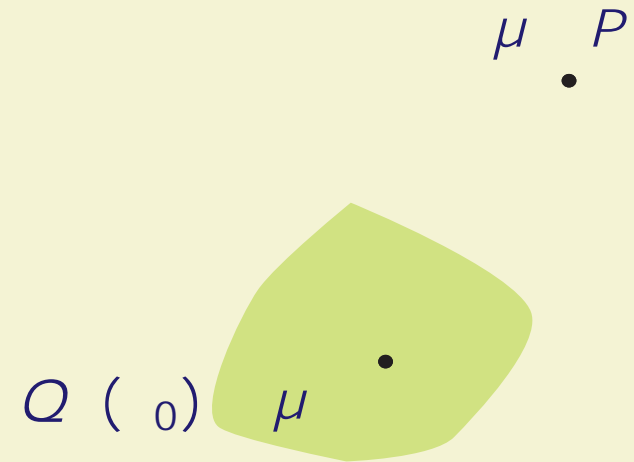
$$\lim_N N^{-1} \log P_0\{L_N = 1\} = -$$

The error probability e^{-N} must be multiplied by e^{NR}

For vanishing error,

$$e^{NR} \times e^{-N} < 1$$

That is, $R < \mu$



Channel Coding and Sanov's Theorem

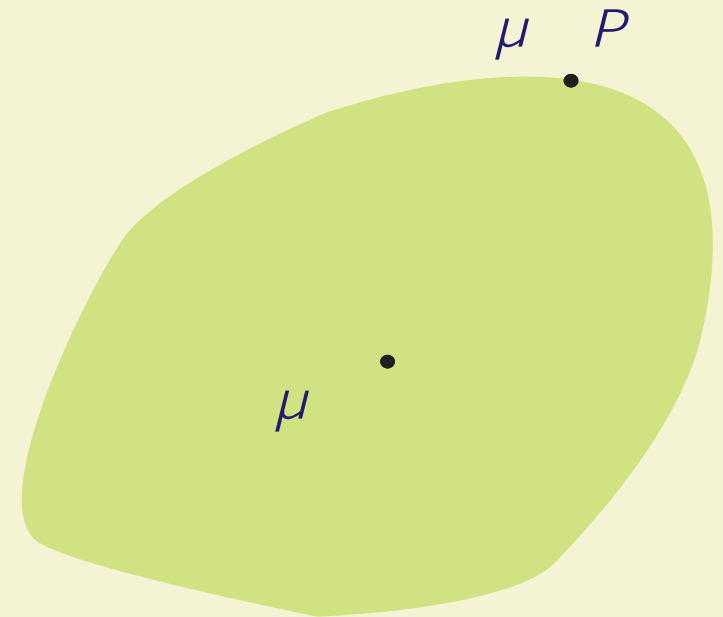
Solution: $\phi = 0$ if $L_n \in Q(\mu)$

$$\lim_N N^{-1} \log P_0\{L_n = 1\} = -$$

The error probability e^{-N} must be multiplied by e^{NR}

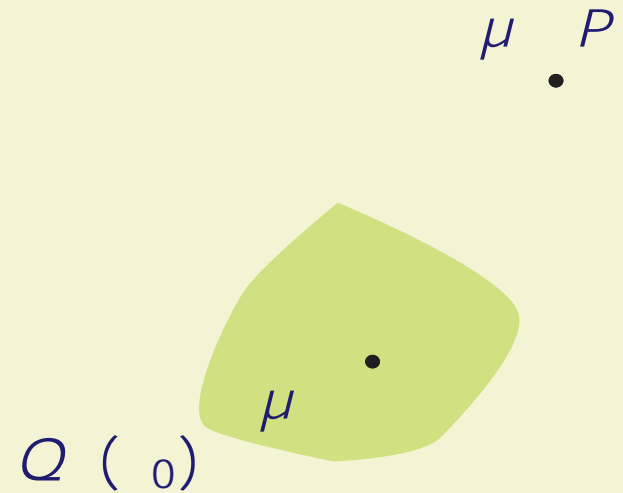
$$R < \max = D(\mu \parallel P) = \text{mutual information}$$

$Q_{\max}(\mu)$



Error Exponent

$$\begin{aligned} E(R, \mu) &= -\lim_N N^{-1} \log P \{ \text{error} \} \\ &= -N^{-1} \log \{ e^{NR} \times e^{-N} \times e^{-N} \} \\ &= -R + \quad + \quad \quad \quad (\text{some } \epsilon, \text{ small } \delta) \end{aligned}$$

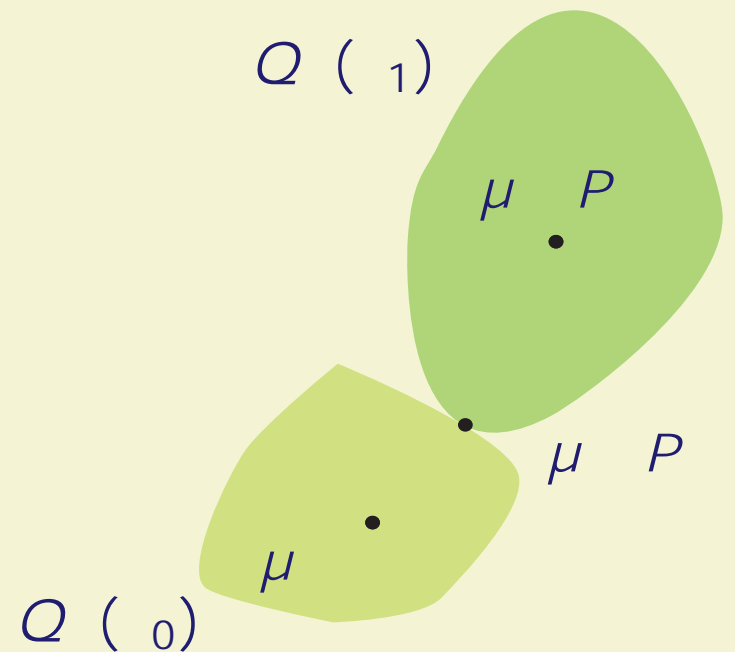


Error Exponent

$$\begin{aligned}
 E(R, \mu) &= -\lim_N N^{-1} \log P \{ \text{error} \} \\
 &= -N^{-1} \log \{ e^{NR} \times e^{-N} \times e^{-N} \} \\
 &= -R + \dots
 \end{aligned}$$

Set = R

$$= E(R, \mu) = \inf_P D(\mu \parallel P)$$



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Summary

Standard coding based on AWGN models

May be unrealistic in wireless models with fading

Discrete distributions arise in coding,
and other applications involving optimization over M

Extremal distributions arise in worst-case models

What's Next?

II Channel models

Convex optimization and channel coding

Cutting plane algorithm

III Worst-case models

Extremal distributions