



*BUS AND DRIVER SCHEDULING IN
URBAN MASS TRANSIT SYSTEMS*

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OVERVIEW

- Introduction
- Bus scheduling
- Driver duty scheduling
- Simultaneous bus and driver scheduling

URBAN BUS TRANSPORTATION

- Provides:
 - Interesting, complex and challenging problems for Operations Research
- Because:
 - Large savings can be realized
 - A large number of resources is involved

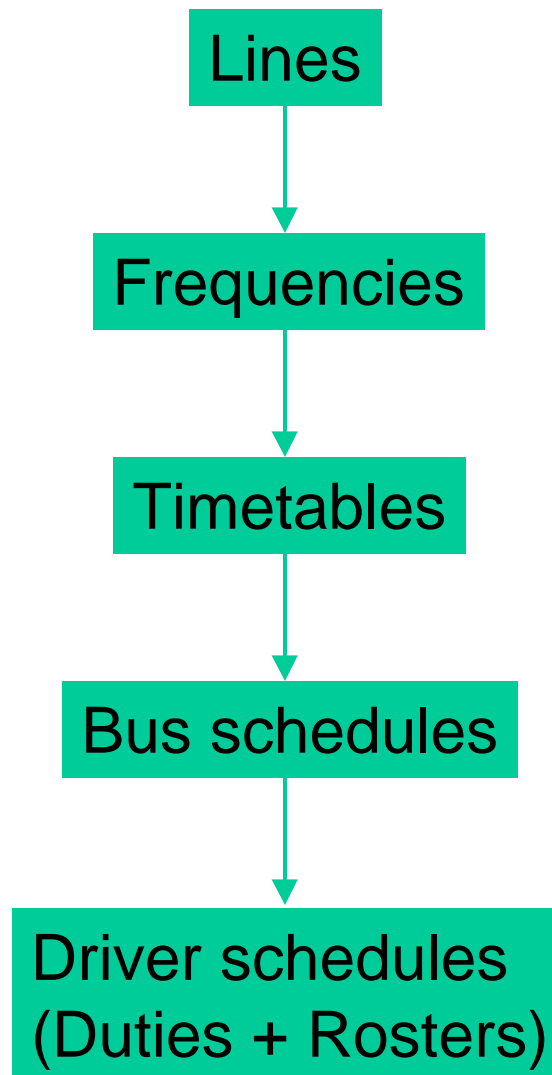
LARGE NUMBERS

	Nb Lines	Nb Buses	Nb Depots
Twin Cities	132	940	5
Montréal	206	1500	7
Paris	246	3860	23
NYC	298	4860	18

Nb of drivers \cong 2-3 x nb of buses

Nb of daily trips \cong 10-20 x nb of buses

OPERATIONS PLANNING PROCESS



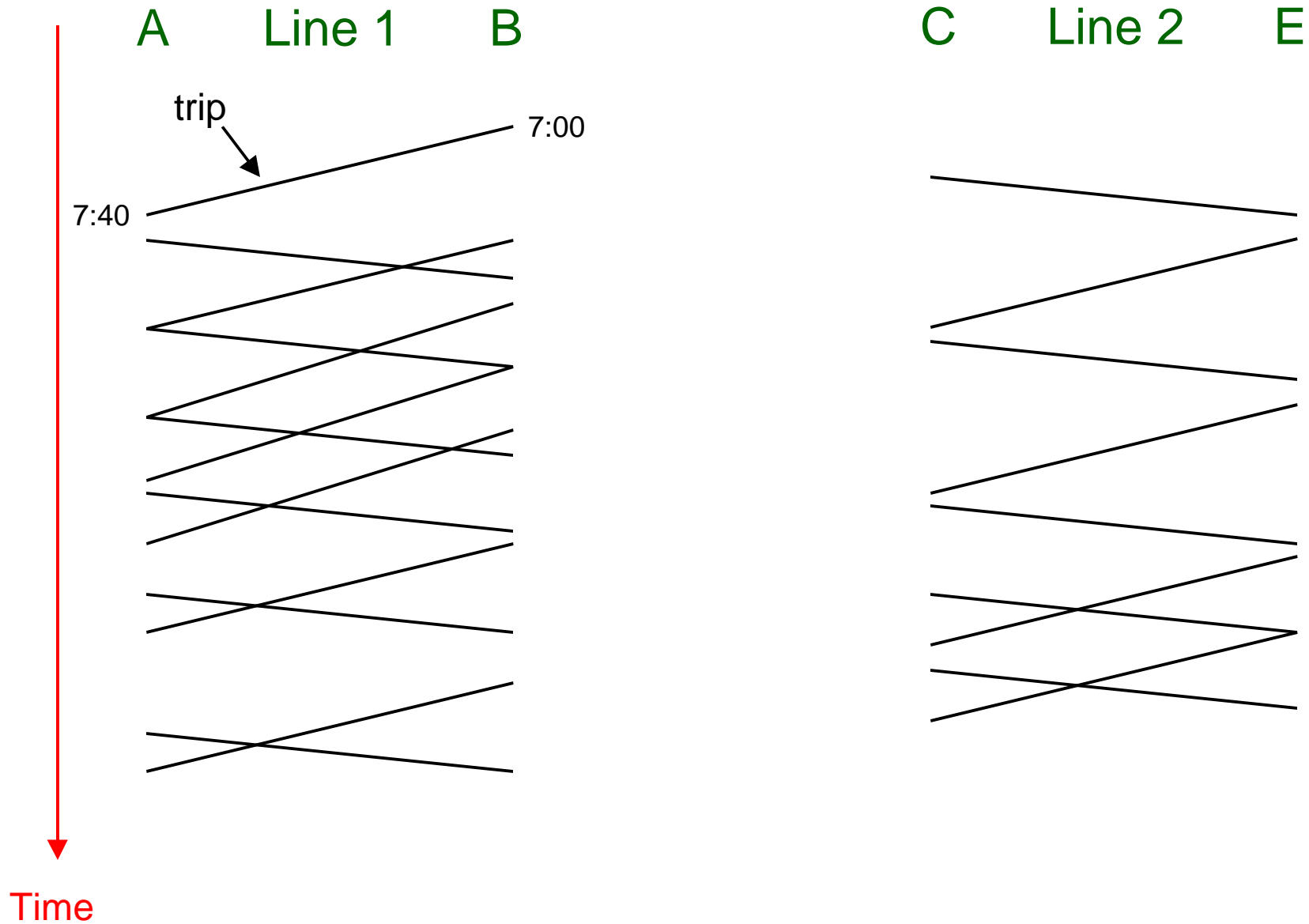
GOAL OF THIS TALK

- Review latest approaches based on mathematical programming for
 - Bus scheduling
 - Duty scheduling
 - Simultaneous bus and duty scheduling
- Where do we stand with these approaches ?

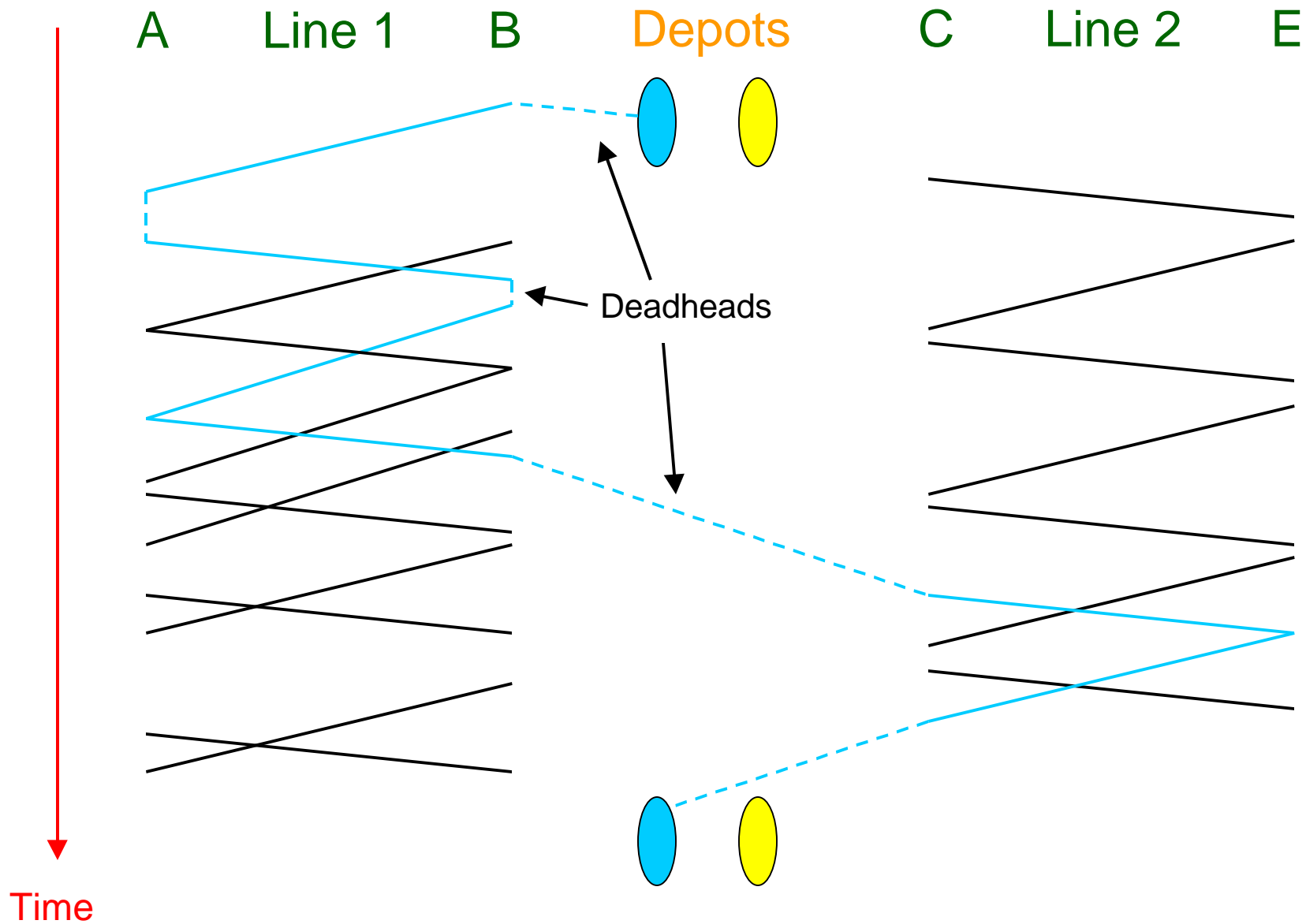
BUS SCHEDULING PROBLEM DEFINITION

- One-day horizon
- Several depots
 - Different locations
 - Different bus types (standard, low floor, reserve lane in opposite direction, ...)

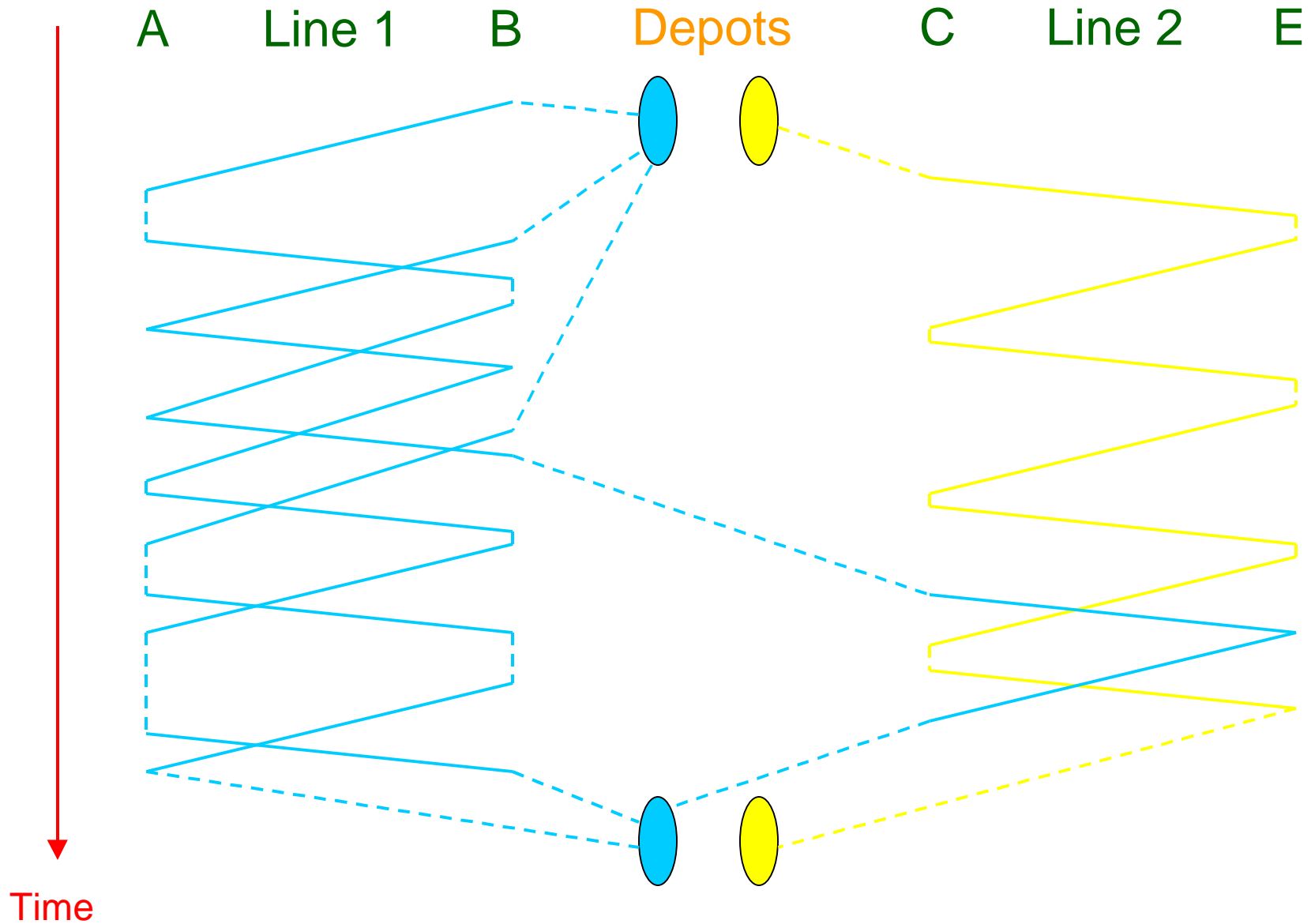
PROBLEM DEFINITION (CONT'D)



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PROBLEM DEFINITION (CONT'D)



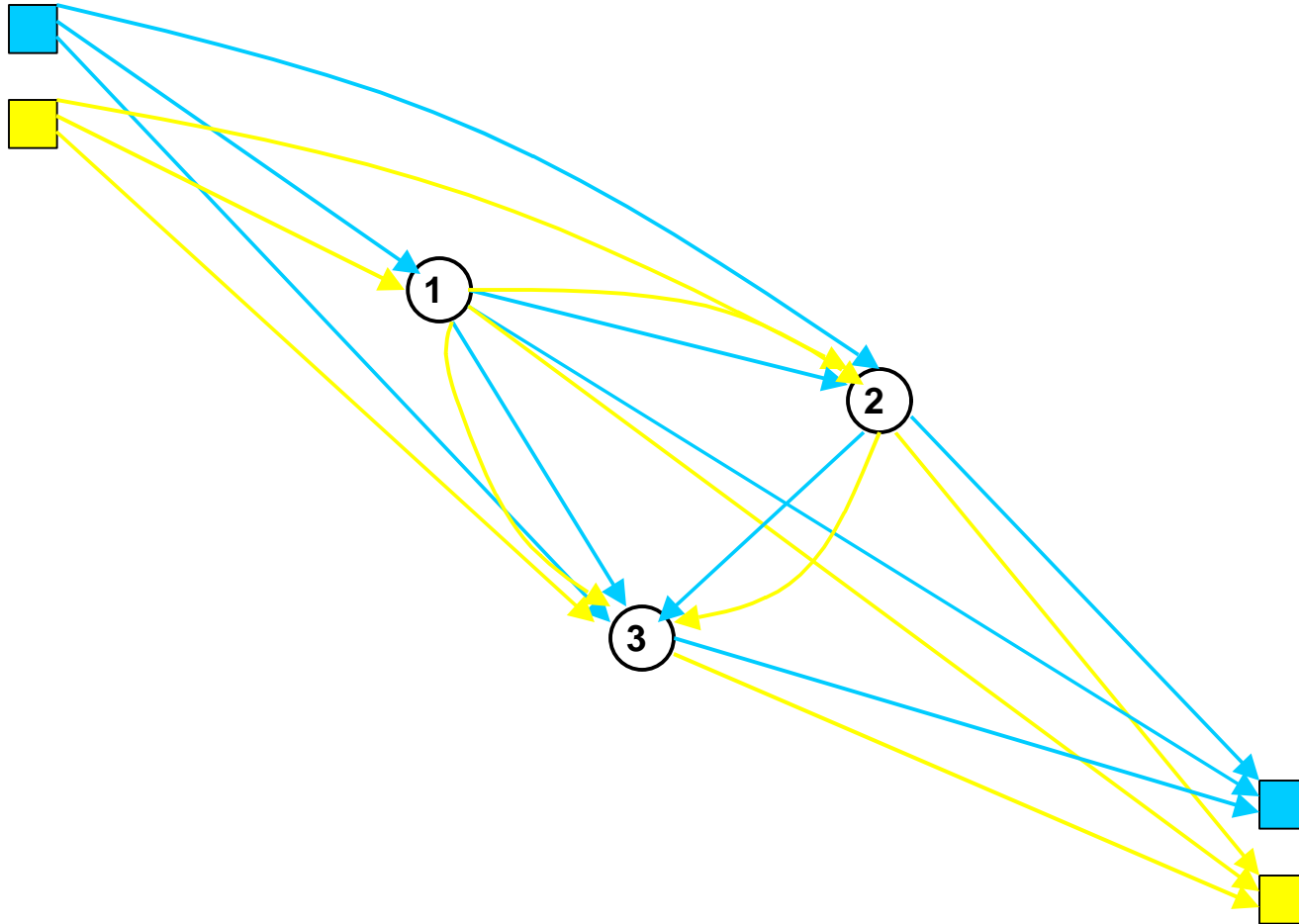
PROBLEM DEFINITION (CONT'D)

- **Constraints**
 - Cover all trips
 - Feasible bus routes
 - ★ Schedule
 - ★ Starts and ends at the same depot
 - Bus availability per depot
 - Depot-trip compatibility
 - Deadhead restrictions

PROBLEM DEFINITION (CONT'D)

- **Objectives:**
 - Minimize the number of buses
 - Minimize deadhead costs
 - ★ Proportional to travel distance or time
 - ★ Fuel, maintenance, driver wages
 - No trip costs

NETWORK STRUCTURE



SOLUTION METHODOLOGIES

- Multi-commodity + column generation
- Set partitioning + branch-and-price-and-cut

A. Löbel (1998)

*Vehicle scheduling in public transit and
lagrangean pricing*

Management Science 44

MULTI-COMMODITY MODEL

$$X_{ij}^k = \begin{cases} 1 & \text{if arc } (i, j) \text{ from depot } k \text{ is chosen} \\ 0 & \text{otherwise} \end{cases}$$

$$\text{Minimize} \quad \sum_{k \in K} \sum_{(i,j) \in A^k} c_{ij} X_{ij}^k$$

$$\text{s.t.} \quad \sum_{k \in K} \sum_{(t,j) \in A^k} X_{tj}^k = 1, \quad \forall t \in T$$

$$\sum_{(o^k,j) \in A^k} X_{o^k,j}^k \leq v^k, \quad \forall k \in K$$

$$\sum_{(t,j) \in A^k} X_{tj}^k - \sum_{(j,t) \in A^k} X_{jt}^k = 0, \quad \forall t \in T, k \in K$$

$$X_{i,j}^k \in \{0, 1\}, \quad \forall k \in K, (i, j) \in A^k$$

COLUMN GENERATION

- On the multi-commodity formulation
- Two pricing strategies
 - Lagrangean pricing
 - Standard
- LP solution is often integer
 - If not, rounding procedure

LAGRANGEAN PRICING

- For fixed dual variables, solve
 - Lagrangean relaxation 1
 - ★ Relax trip covering constraints
 - ★ Obtain a minimum cost flow problem
 - Lagrangean relaxation 2
 - ★ Relax flow conservation and depot capacity constraints
 - ★ Add
$$\sum_{k \in K} \sum_{(j,t) \in A^k} X_{jt}^k = 1, \quad \forall t \in T$$
 - ★ Obtain a simple problem that can be solved by inspection

RESULTS

- Real-world instances

Depots	Trips	Depots/trip	CPU (hrs.)
4	3,413	1.7	0.7
9	2,424	4.9	12
12	8,563	2.2	14
49	24,906	1.6	10*

* Not to optimality

*A. Hadjar, O. Marcotte,
F. Soumis (2001)*

*A branch-and-cut approach for the multiple
depot vehicle scheduling problem*

Les Cahiers du GERAD, G-2001-25

SET PARTITIONING MODEL

$$\theta_p^k = \begin{cases} 1 & \text{if route } p \text{ from depot } k \text{ is chosen} \\ 0 & \text{otherwise} \end{cases}$$

$$\text{Minimize} \quad \sum_{k \in K} \sum_{p \in \Omega^k} c_p \theta_p^k$$

$$\text{s.t.} \quad \sum_{k \in K} \sum_{p \in \Omega^k} a_{tp} \theta_p^k = 1, \quad \forall t \in T$$

$$\sum_{p \in \Omega^k} \theta_p^k \leq v^k, \quad \forall k \in K$$

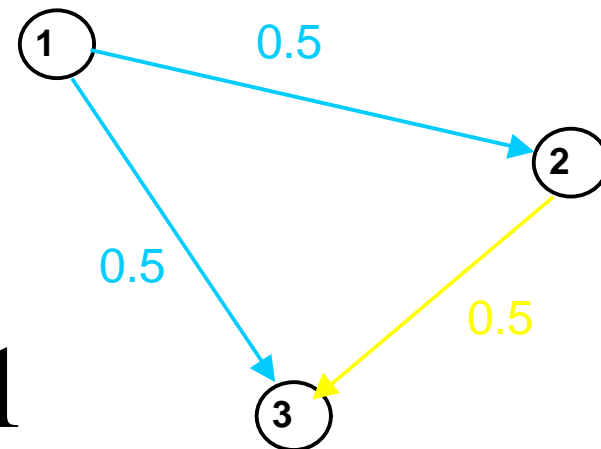
$$\theta_p^k \in \{0, 1\}, \quad \forall k \in K, p \in \Omega^k$$

BRANCH-AND-PRICE-AND-CUT

- Arc elimination throughout the search tree
 - Heuristic feasible initial solution
 - Reduced cost test $\bar{c}_{ij}^k \geq z_{IP}^{cur} - \pi^T b$

- Odd cycle cuts
(facets)

$$X_{12}^b + X_{13}^b + X_{23}^y \leq 1$$



RESULTS

- Randomly generated instances

Depots	Trips	Depots/trip	CPU (hrs.)
2	900	2	2.5
4	500	4	3
6	500	6	5

VARIANTS

- Fueling constraints
- Departure time windows
 - Desaulniers, Lavigne, and Soumis (1998)
 - Bianco, Mingozzi, Ricciardelli (1995)
- Departure time windows and waiting costs
 - Desaulniers, Lavigne, and Soumis (1998)

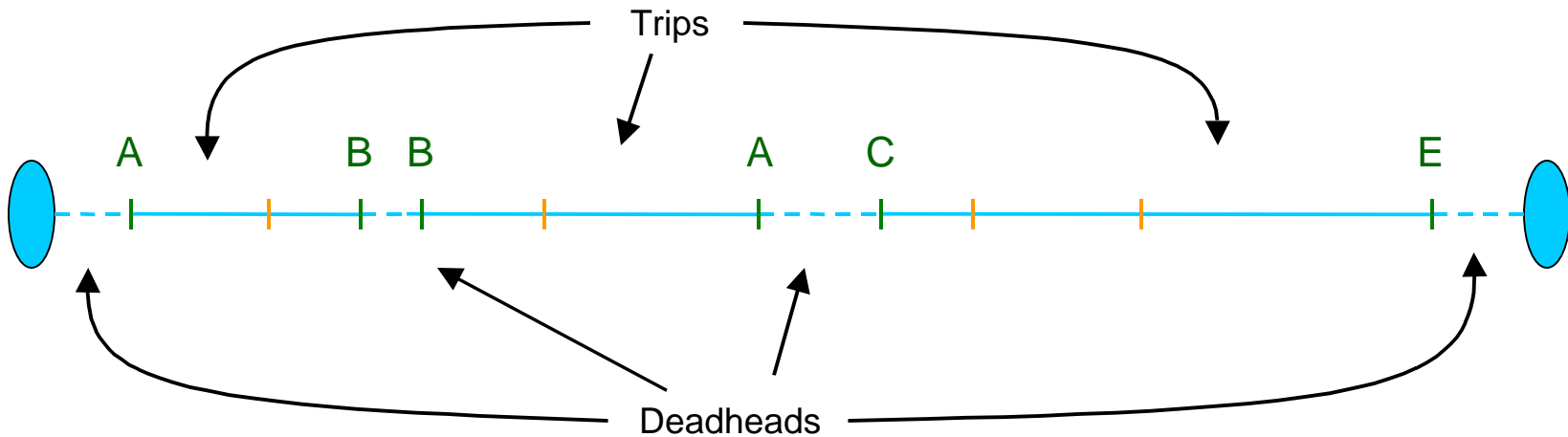
DUTY SCHEDULING PROBLEM DEFINITION

- One-day horizon
- One depot

- Bus blocks are known
- Bus deadheads are known

PROBLEM DEFINITION (CONT'D)

One bus block

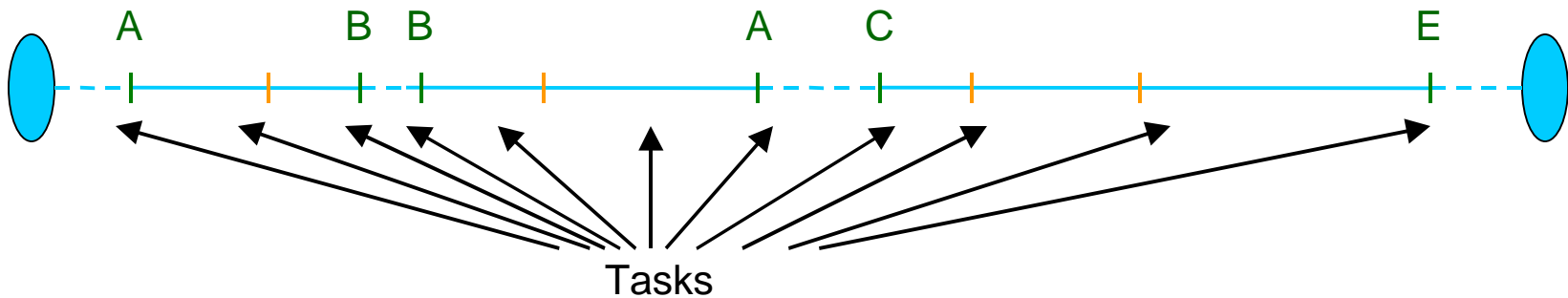


Relief point: location where a change of driver can occur

Relief points: all termini
additional locations

PROBLEM DEFINITION (CONT'D)

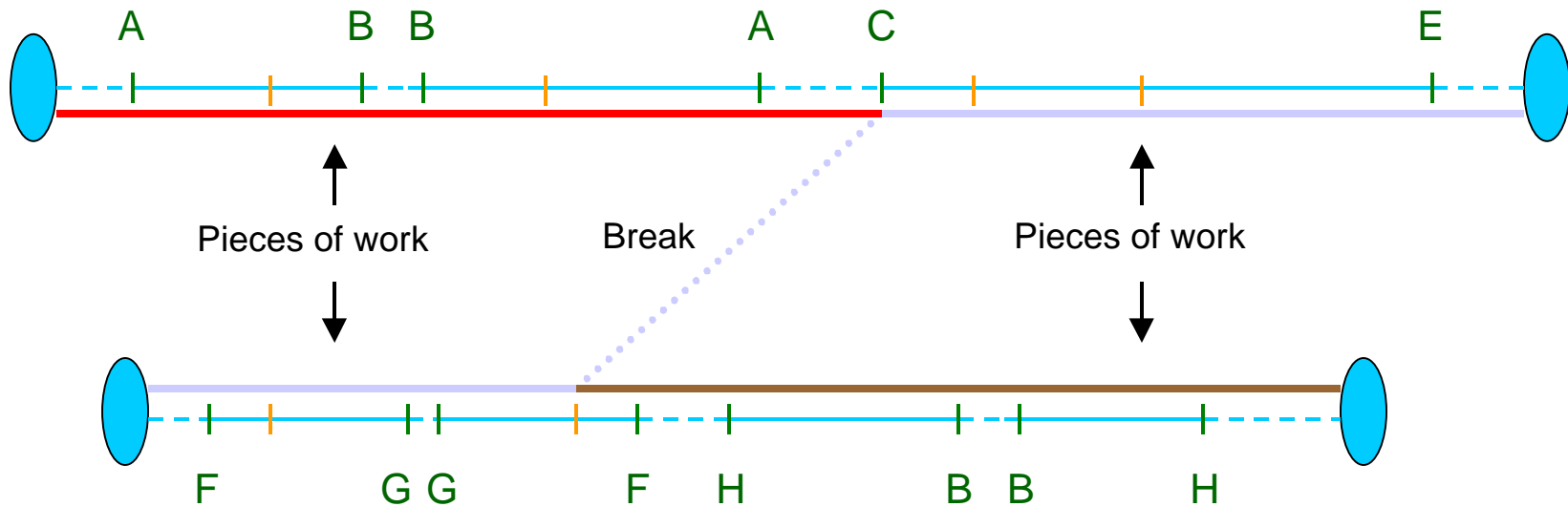
One bus block



Task: indivisible portion of work between two consecutive relief points along a bus block

Trip tasks and deadhead tasks

PROBLEM DEFINITION (CONT'D)



Duty: Sequence of tasks assigned to a driver

Piece of work: Subsequence of tasks on the same block

Duty type: Depends on work regulations

PROBLEM DEFINITION (CONT'D)

- **Constraints**
 - Cover all tasks (continuous attendance)
 - Feasible duties
 - ★ Schedule
 - ★ Work regulations for each duty type
 - Number of pieces
 - Min and max piece duration
 - Min and max break duration
 - Min and max working time
 - Valid start time interval
 - Min number of duties of each type

PROBLEM DEFINITION (CONT'D)

- **Objectives**
 - Minimize the number of duties
 - Minimize total wages

SET PARTITIONING MODEL

$$Y_d^u = \begin{cases} 1 & \text{if duty } d \text{ of type } u \text{ is chosen} \\ 0 & \text{otherwise} \end{cases}$$

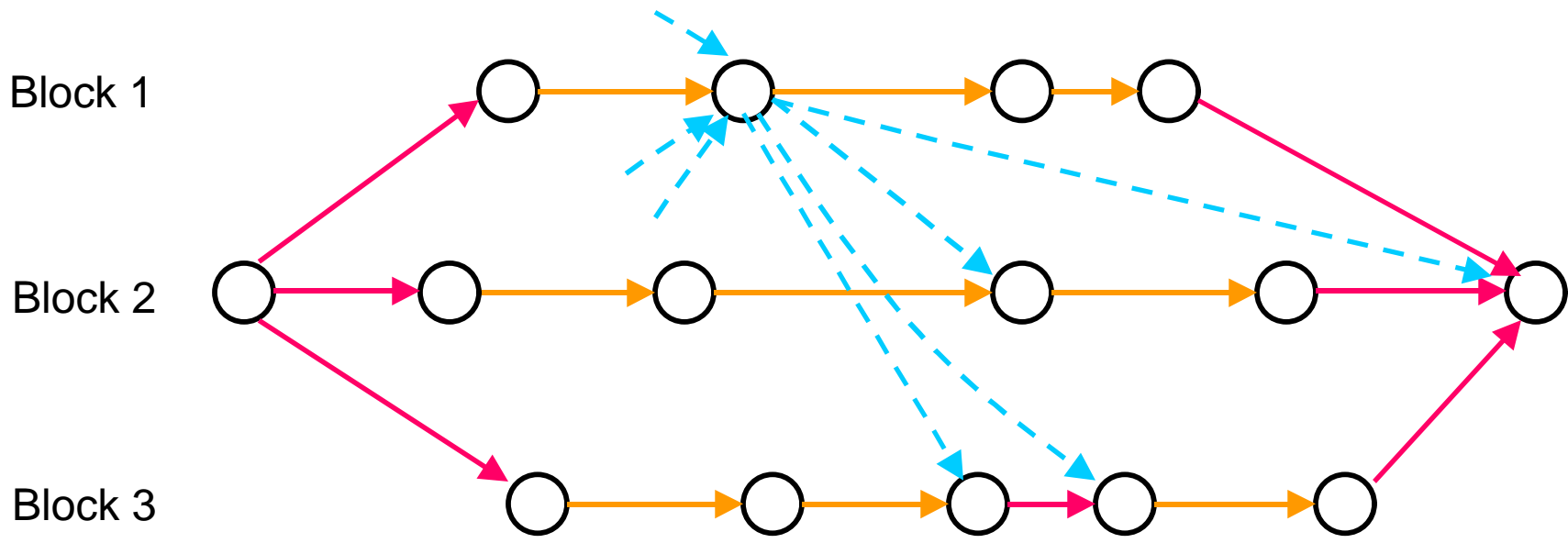
$$\text{Minimize} \quad \sum_{u \in U} \sum_{d \in \Delta^u} c_d Y_d^u$$




$$\text{s.t.} \quad \sum_{u \in U} \sum_{d \in \Delta^u} a_{sd} Y_d^u = 1, \quad \forall s \in S$$

$$\sum_{d \in \Delta^u} Y_d^u \geq n_u, \quad \forall u \in U$$

$$Y_d^u \in \{0, 1\}, \quad \forall u \in U, d \in \Delta^u$$

NETWORK STRUCTURE



-  Trip task
-  Deadhead task
-  Walking

Resource constraints are used to model working rules

SOLUTION METHODOLOGY

- Heuristic branch-and-price

*R. Borndörfer, M. Grötschel,
A. Löbel (2001)*

*Scheduling duties by adaptive column
generation*

*ZIB-Report 01-02
Konrad-Zuse-Zentrum für
Informationstchnik, Berlin*

HEURISTIC BRANCH-AND-PRICE

- Master problem solved by Lagrangean relaxation
- Constrained shortest path subproblem solved by
 - Backward depth-first search enumeration algorithm
 - Lagrangean lower bounds are used to eliminate possibilities

HEURISTIC BRANCH-AND-PRICE

- Depth-first branch-and-bound
 - At each node, 20 candidate columns are selected
 - Probing is performed for each candidate
 - One variable is fixed at each node
 - No new columns are generated if the decision made does not deteriorate too much the objective function value

RESULTS

- 1065 tasks
- 3 duty types
- 1h20 of CPU time
- Reduction in number of duties from 73 to 63

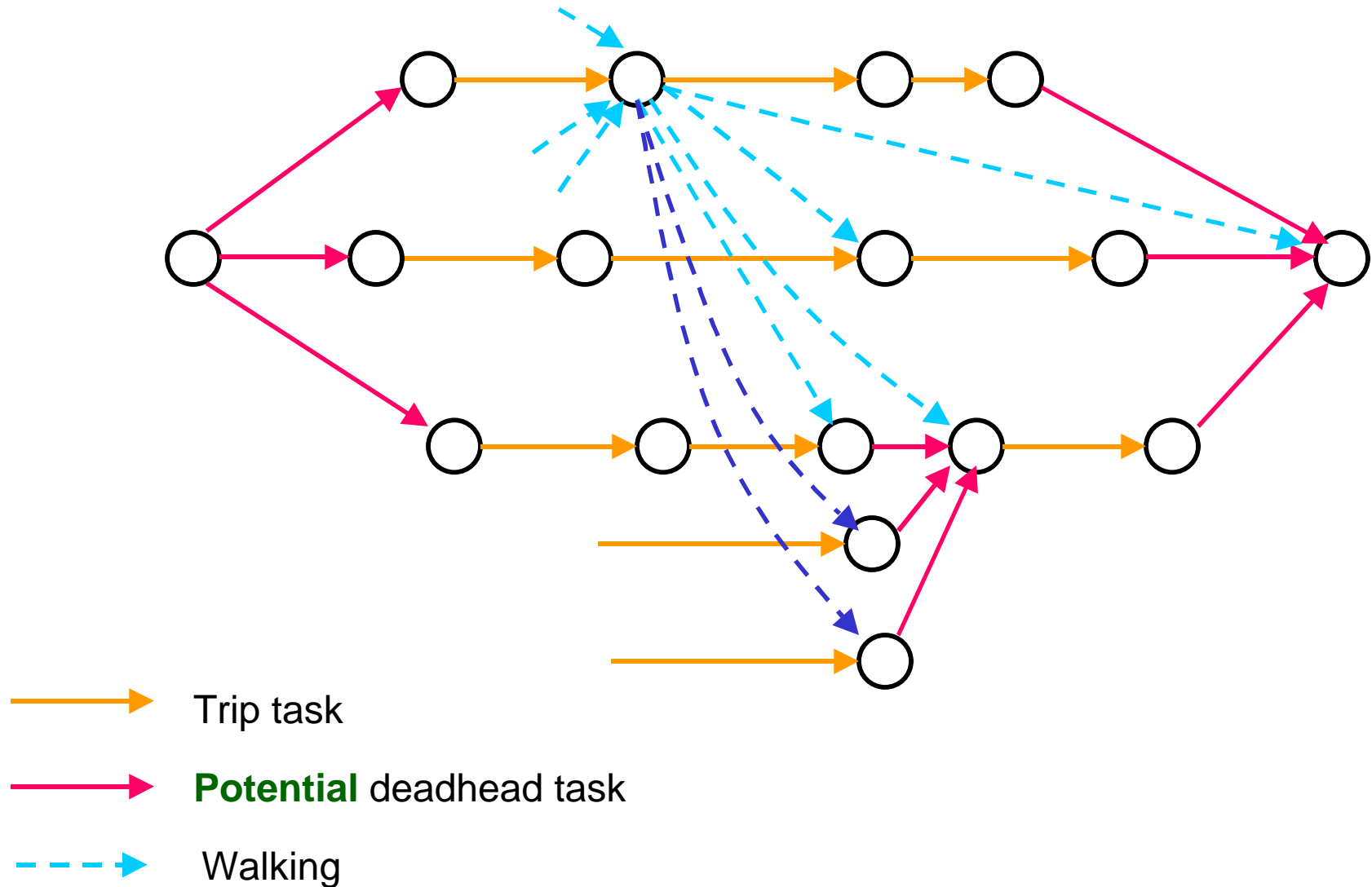
SIMULTANEOUS BUS AND DUTY SCHEDULING – PROBLEM DEFINITION

- One-day horizon
- One depot
- Bus blocks are unknown
 - ⇒ Bus deadheads are unknown

PROBLEM DEFINITION (CONT'D)

- Find
 - Feasible bus blocks
 - Feasible duties
- Such that
 - Each trip is covered by a bus
 - Each trip task is covered by a driver
 - Each **selected** deadhead task is covered by a driver

BUS AND DUTY SCHEDULING NETWORK STRUCTURE



SOLUTION METHODOLOGIES

- Mixed set partitioning / flow model
+ column generation / heuristic
- Set partitioning + branch-and-price

*R. Freling, D. Huisman,
A.P.M. Wagelmans (2000)*

*Models and algorithms for integration of
vehicle and crew scheduling*

*Econometric Institute Report EI2000-10/A
Erasmus University, Rotterdam*

MIXED SET PARTITIONING / FLOW MODEL

$$\begin{aligned} \text{Minimize} \quad & \sum_{(i,j) \in A} c_{ij} X_{ij} + \sum_{u \in U} \sum_{d \in \Delta^u} c_d Y_d^u \\ \text{s.t.} \quad & \sum_{(t,j) \in A} X_{tj} = 1, \quad \forall t \in T \\ & \sum_{(i,t) \in A} X_{it} = 1, \quad \forall t \in T \\ & \sum_{u \in U} \sum_{d \in \Delta^u} a_{sd} Y_d^u = 1, \quad \forall s \in S^T \\ & \sum_{u \in U} \sum_{d \in \Delta^u} b_{ijd} Y_d^u - X_{ij} = 0, \quad \forall (i,j) \in A \\ & Y_d^u \in \{0,1\}, \quad \forall u \in U, d \in \Delta^u \\ & X_{ij} \in \{0,1\}, \quad \forall (i,j) \in A \end{aligned}$$

COLUMN GENERATION / HEURISTIC

- LP relaxation is solved by column generation
 - Master problem is solved by Lagrangean relaxation
 - ★ Relax all driver-related constraints
 - ★ Obtain a single-depot bus scheduling problem
 - Pricing problem is solved in two phases
 - ★ Solve an all-pairs shortest path problem to generate pieces of work
 - ★ Combine these pieces to form negative reduced cost feasible duties

COLUMN GENERATION / HEURISTIC

- Once the LP relaxation is solved
 - Fix the bus blocks as computed in the last master problem
 - Solve a duty scheduling problem by column generation

RESULTS

- Real-world instances

Trips	Trip tasks	Gap (%)	CPU (hrs.)
113	113	0.0	0.33
148	148	2.9	1.5
238	238	3.6	67.8

*K. Haase, G. Desaulniers,
J. Desrosiers (2001)*

*Simultaneous vehicle and crew scheduling
in urban mass transit systems*

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SET PARTITIONING MODEL

$$\text{Minimize} \quad cB + \sum_{u \in U} \sum_{d \in \Delta^u} c_d Y_d^u$$

$$\text{s.t.} \quad \sum_{u \in U} \sum_{d \in \Delta^u} b_{td}^{\text{DH}} Y_d^u = 1, \quad \forall t \in T$$

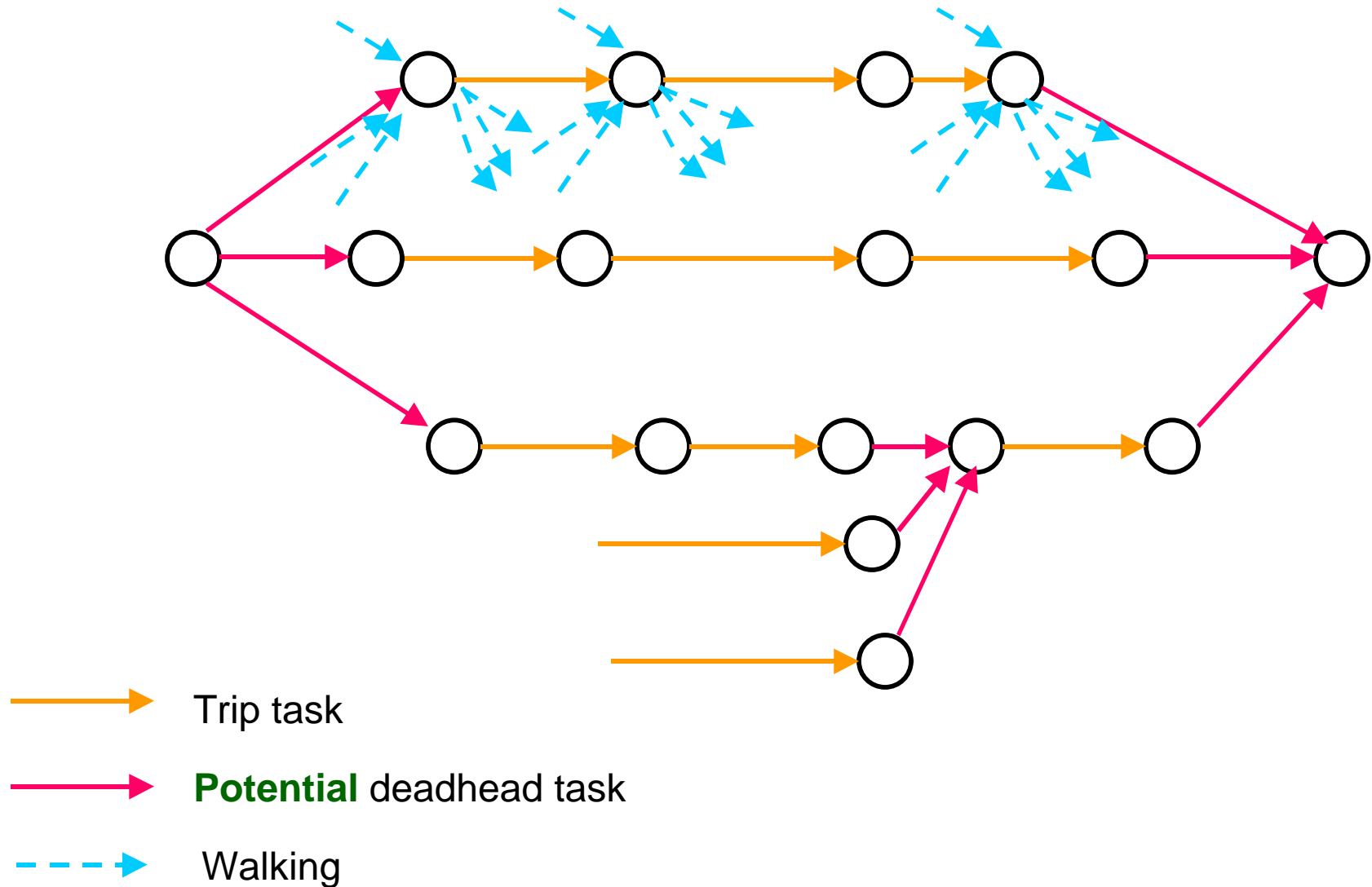
$$\sum_{u \in U} \sum_{d \in \Delta^u} (b_{sd}^{\text{WI}} - b_{sd}^{\text{WO}}) Y_d^u = 0, \quad \forall s \in S^T$$

$$\sum_{u \in U} \sum_{d \in \Delta^u} (e_{td}^{\text{WI}} - e_{td}^{\text{WO}}) Y_d^u = 0, \quad \forall t \in T$$

$$\sum_{u \in U} \sum_{d \in \Delta^u} q_{hd} Y_d^u \leq B, \quad \forall h \in H$$

$$Y_d^u \in \{0, 1\}, \quad \forall u \in U, d \in \Delta^u$$

BUS AND DUTY SCHEDULING NETWORK STRUCTURE



EXACT BRANCH-AND-PRICE

- Bus constraints are generated dynamically
- Multiple subproblems
 - One per duty type and possible start duty time
 - Partial pricing
- Exact branching strategies

HEURISTIC BRANCH-AND-PRICE

- Early LP termination
- Depth-first search without backtracking
- Multiple branching decisions on columns

EXACT RESULTS

- Real-world instances
- Minimize number of duties

Trips	Trip tasks	Gap (%)	CPU (min.)
85	170	7.1	0.7
143	286	0	5.9
177	354	0	43.1
204	408	0	192.6
262	524	0	354.7

HEURISTIC RESULTS

- Real-world instances
- Minimize number of duties

Trips	Trip tasks	Gap (%)	CPU (min.)
177	354	4.1	5.3
204	408	0	8.2
262	524	0	36.1
378	756	2.0	70.3
463	926	0.2	199.2

VARIANTS

- Parkings
- Multiple depots
 - Desaulniers (2001), TRISTAN
 - Huisman (2002), IFORS

FUTURE RESEARCH ON SIMULTANEOUS BUS AND DUTY SCHEDULING

- Reducing solution times
 - For master problem
 - ★ Dual variable stabilization
 - For constrained shortest path subproblems
 - ★ Generate pieces of work instead of duties
- Target duty working time (in progress)
- Multiple depots (started)
- Integrate timetabling aspects

CONCLUSION

- Bus scheduling
 - Optimal or close-to-optimal solutions for large to very large instances
- Duty scheduling
 - Good solutions for medium to large instances
- Simultaneous bus and duty scheduling
 - Optimal or close-to-optimal solutions for small to medium instances

GILBERT'S MEASURE

Accuracy: very high

Speed: low to medium

Simplicity: very low

Flexibility: medium to high

THANK YOU !

