

# Information and Statistics

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*On Information Theory and Concentration Phenomena*

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- **Information and Probability:**
  - Monotonicity of Information
  - Large Deviation Exponents
  - Central Limit Theorem
- **Information and Statistics:**
  - Nonparametric Rates of Estimation
  - Minimum Description Length Principle
  - Penalized Likelihood (one-sided concentration)
  - Implications for Greedy Term Selection
- **Achieving Shannon Capacity:**
  - Sparse Superposition Coding
  - Adaptive Successive Decoding
  - Rate, Reliability, and Computational Complexity

- **Information and Probability:**
  - Monotonicity of Information
  - Markov chains, martingales
  - Central Limit Theorem
  - Entropy and Fisher Information Inequalities
  - Information Stability (asymptotic equipartition property)
  - Large Deviation Exponents (law of large numbers)

# Monotonicity of Information Divergence

- Information Inequality  $X \rightarrow X'$

$$D(P_{X'} \| P_{X'}^*) \leq D(P_X \| P_X^*)$$

- Chain Rule

$$\begin{aligned} D(P_{X, X'} \| P_{X, X'}^*) &= D(P_{X'} \| P_{X'}^*) + E D(P_{X|X'} \| P_{X|X'}^*) \\ &= D(P_X \| P_X^*) + E D(P_{X'|X} \| P_{X'|X}^*) \end{aligned}$$

- Markov Chain  $\{X_n\}$  with  $P^*$  invariant

$$D(P_{X_n} \| P^*) \leq D(P_{X_m} \| P^*) \quad \text{for } n > m$$

- Convergence

$\log p_n(X_n)/p^*(X_n)$  is a Cauchy sequence in  $L_1(P)$

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- Pinsker-Kullback-Csiszar inequalities

$$A \leq D + \sqrt{2D} \quad V \leq \sqrt{2D}$$

# Martingale Convergence and Limits of Information

- Nonnegative Martingales  $\rho_n$  correspond to the density of a measure  $Q_n$  given by  $Q_n(A) = E[\rho_n 1_A]$ .
- Limits can be established in the same way by the chain rule for  $n > m$

$$D(Q_n \| P) = D(Q_m \| P) + \int \left( \rho_n \log \frac{\rho_n}{\rho_m} \right) dP$$

- Thus  $D_n = D(Q_n \| P)$  is an increasing sequence. Suppose it is bounded.
- Then  $\rho_n$  is a Cauchy sequences in  $L_1(P)$  with limit  $\rho$  defining a measure  $Q$
- Also,  $\log \rho_n$  is a Cauchy sequence in  $L_1(Q)$  and

$$D(Q_n \| P) \nearrow D(Q \| P)$$

# Monotonicity of Information Divergence: CLT

- Central Limit Theorem Setting:

$\{X_i\}$  i.i.d. mean zero, finite variance

$P_n = P_{Y_n}$  is distribution of  $Y_n = \frac{X_1 + X_2 + \dots + X_n}{\sqrt{n}}$

$P^*$  is the corresponding normal distribution

- For  $n > m$

$$D(P_n \| P^*) < D(P_m \| P^*)$$

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- Chain Rule for  $n > m$ : not clear how to use in this case

$$\begin{aligned} D(P_{Y_m, Y_n} \| P_{Y_m, Y_n}^*) &= D(P_{Y_n} \| P^*) + ED(P_{Y_m | Y_n} \| P_{Y_m | Y_n}^*) \\ &= D(P_{Y_m} \| P^*) + ED(P_{Y_n | Y_m} \| P_{Y_n | Y_m}^*) \end{aligned}$$

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- Entropy Power Inequality

$$e^{2H(X+X')} \geq e^{2H(X)} + e^{2H(X')}$$

yields

$$D(P_{2n} \| P^*) \leq D(P_n \| P^*)$$

- Information Theoretic proof of CLT (B. 1986):

$$D(P_n \| P^*) \rightarrow 0 \text{ iff finite}$$

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- (Johnson and B. 2004) with Poincare constant  $R$

$$D(P_n \| P^*) \leq \frac{2R}{n-1+2R} D(P_1 \| P^*)$$

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- (Bobkov, Chirstyakov, Gotze 2013) Moment conditions and finite  $D(P_1 \| P^*)$  suffice for this  $1/n$  rate

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- Entropy Power Inequality

$$e^{2H(X+X')} \geq e^{2H(X)} + e^{2H(X')}$$

- Generalized Entropy Power Inequality (Madiman&B.2006)

$$e^{H(X_1+\dots+X_n)} \geq \frac{1}{r} \sum_{s \in \mathcal{S}} e^{2H(\sum_{i \in s} X_i)}$$

where  $r$  is max number of sets in  $\mathcal{S}$  in which an index appears

- Proof:
  - simple  $L_2$  projection property of entropy derivative
  - concentration inequality for sums of functions of subsets of independent variables

$$\text{VAR}\left(\sum_{s \in \mathcal{S}} g_s(X_s)\right) \leq r \sum_{s \in \mathcal{S}} \text{VAR}(g_s(X_s))$$

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- Consequence, for all  $n > m$ ,

$$D(P_n \| P^*) \leq D(P_m \| P^*)$$

[Madiman and B. 2006, Tolino and Verdú 2006.

Earlier elaborate proof by Artstein, Ball, Barthe, Naor 2004]

- Stability of log-likelihood ratios (AEP)  
(B. 1985, Orey 1985, Cover and Algoet 1986)

$$\frac{1}{n} \log \frac{p(Y_1, Y_2, \dots, Y_n)}{q(Y_1, Y_2, \dots, Y_n)} \rightarrow \mathcal{D}(P\|Q) \text{ with } P \text{ prob } 1$$

where  $\mathcal{D}(P\|Q)$  is the relative entropy rate.

- Optimal statistical test: critical region  $A_n$  has asymptotic  $P$  power 1 (at most finitely many mistakes  $P(A_n^c \text{ i.o.}) = 0$ ) and has optimal  $Q$ -prob of error

$$Q(A_n) = \exp\{-n[\mathcal{D} + o(1)]\}$$

- General form of the Chernoff-Stein Lemma.
- Relative entropy rate

$$\mathcal{D}(P\|Q) = \lim \frac{1}{n} D(P_{\underline{Y}^n} \| Q_{\underline{Y}^n})$$

# Information-Stability and Error Probability of Tests

- Stability of log-likelihood ratios (AEP)  
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- Relative entropy rate

$$\mathcal{D} = \lim \frac{1}{n} D(P_{\underline{Y}^n} \| Q_{\underline{Y}^n})$$

# Optimality of the Relative Entropy Exponent

- Information Inequality, for any set  $A_n$ ,

$$D(P_{\underline{Y}^n} \| Q_{\underline{Y}^n}) \geq P(A_n) \log \frac{P(A_n)}{Q(A_n)} + P(A_n^c) \log \frac{P(A_n^c)}{Q(A_n^c)}$$

- Consequence

$$D(P_{\underline{Y}^n} \| Q_{\underline{Y}^n}) \geq P(A_n) \log \frac{1}{Q(A_n)} - H_2(P(A_n))$$

- Equivalently

$$Q(A_n) \geq \exp \left\{ - \frac{D(P_{\underline{Y}^n} \| Q_{\underline{Y}^n}) - H_2(P(A_n))}{P(A_n)} \right\}$$

- For any sequence of pairs of joint distributions, no sequence of tests with  $P(A_n)$  approaching 1 can have better  $Q(A_n)$  exponent than  $D(P_{\underline{Y}^n} \| Q_{\underline{Y}^n})$ .

# Large Deviations, I-Projection, and Conditional Limit

- $P^*$ : **Information projection** of  $Q$  onto convex  $C$
- Pythagorean identity (Csiszar 75, Topsøe 79): For  $P$  in  $C$

$$D(P\|Q) \geq D(C\|Q) + D(P\|P^*)$$

where

$$D(C\|Q) = \inf_{P \in C} D(P\|Q)$$

- Empirical distribution  $P_n$ , from i.i.d. sample.
- (Csiszar 1985)

$$Q\{P_n \in C\} \leq \exp\{-nD(C\|Q)\}$$

- Information-theoretic representation of Chernoff bound (when  $C$  is a half-space)



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- Empirical distribution  $P_n$ , from i.i.d. sample
- If  $D(\text{interior}C\|Q) = D(C\|Q)$  then

$$Q\{P_n \in C\} = \exp \{ -n [D(C\|Q) + o(1)] \}$$

and the conditional distribution  $P_{Y_1, Y_2, \dots, Y_n | \{P_n \in C\}}$  converges to  $P_{Y_1, Y_2, \dots, Y_n}^*$  in the I-divergence rate sense (Csiszar 1985)

## Information and Statistics:

- Nonparametric Rates of Estimation
- Minimum Description Length Principle
- Penalized Likelihood (one-sided concentration)
- Implications for Greedy Term Selection

- Capacity
  - A Channel  $\theta \rightarrow \underline{Y}$  is a family of distributions  $\{P_{\underline{Y}|\theta} : \theta \in \Theta\}$
  - Information Capacity:  $C = \max_{P_\theta} I(\theta; \underline{Y})$
- Communications Capacity
  - Thm:  $C_{com} = C$  (Shannon 1948)
- Data Compression Capacity
  - Minimax Redundancy:  $Red = \min_{Q_{\underline{Y}}} \max_{\theta \in \Theta} D(P_{\underline{Y}|\theta} \| Q_{\underline{Y}})$
  - Data Compression Capacity Theorem:  $Red = C$   
(Gallager, Davisson & Leon-Garcia, Ryabko)

## Statistical Risk Setting

- Loss function

$$\ell(\theta, \theta')$$

- Kullback loss

$$\ell(\theta, \theta') = D(P_{Y|\theta} \| P_{Y|\theta'})$$

- Squared metric loss, e.g. squared Hellinger loss:

$$\ell(\theta, \theta') = d^2(\theta, \theta')$$

- Statistical risk equals expected loss

$$\text{Risk} = E[\ell(\theta, \hat{\theta})]$$

## Statistical Capacity

- Estimators:  $\hat{\theta}_n$
- Based on sample  $\underline{Y}$  of size  $n$
- Minimax Risk (Wald):

$$r_n = \min_{\hat{\theta}_n} \max_{\theta} E\ell(\theta, \hat{\theta}_n)$$

## Ingredients in Determining Minimax Rates of Statistical Risk

- Kolmogorov Metric Entropy of  $S \subset \Theta$ :

$$H(\epsilon) = \max\{\log \text{Card}(\Theta_\epsilon) : d(\theta, \theta') > \epsilon \text{ for } \theta, \theta' \in \Theta_\epsilon \subset S\}$$

- Loss Assumption, for  $\theta, \theta' \in S$ :

$$\ell(\theta, \theta') \sim D(P_{Y|\theta} \| P_{Y|\theta'}) \sim d^2(\theta, \theta')$$

## Information-theoretic Determination of Minimax Rates

- For infinite-dimensional  $\Theta$
- With metric entropy evaluated a critical separation  $\epsilon_n$
- Statistical Capacity Theorem

Minimax Risk  $\sim$  Info Capacity Rate  $\sim$  Metric Entropy rate

$$r_n \sim \frac{C_n}{n} \sim \frac{H(\epsilon_n)}{n} \sim \epsilon_n^2$$

(Yang 1997, Yang and B. 1999, Haussler and Opper 1997)



Minimum Description-Length (Rissanen78,83,B.85, B.&Cover 91...)

- Statistical measure of complexity of  $\underline{Y}$

$$L(\underline{Y}) = \min_q \left[ \log 1/q(\underline{Y}) + L(q) \right]$$

bits for  $\underline{Y}$  given  $q$  + bits for  $q$

- It is an information-theoretically valid codelength for  $\underline{Y}$  for any  $L(q)$  satisfying Kraft summability  $\sum_q 2^{-L(q)} \leq 1$ .
- The minimization is for  $q$  in a family indexed by parameters  $\{p_\theta(\underline{Y}) : \theta \in \Theta\}$  or by functions  $\{p_f(\underline{Y}) : f \in \mathcal{F}\}$
- The estimator  $\hat{p}$  is then  $p_{\hat{\theta}}$  or  $p_{\hat{f}}$ .

- From training data  $\underline{x}$   $\Rightarrow$  estimator  $\hat{p}$
- Generalize to subsequent data  $\underline{x}'$
- Want  $\log 1/\hat{p}(\underline{x}')$  to compare favorably to  $\log 1/p(\underline{x}')$
- For targets  $p$  close to or in the families
- With  $\underline{X}'$  expectation, loss becomes Kullback divergence
- Bhattacharyya, Hellinger, Rényi loss also relevant

- Kullback Information-divergence:

$$D(P_{\underline{X}'} \| Q_{\underline{X}'}) = E[ \log p(\underline{X}')/q(\underline{X}') ]$$

- Bhattacharyya, Hellinger, Rényi divergence:

$$d^2(P_{\underline{X}'}, Q_{\underline{X}'}) = 2 \log 1 / E[q(\underline{X}')/p(\underline{X}')]^{1/2}$$

- Product model case:  $D(P_{\underline{X}'} \| Q_{\underline{X}'}) = n D(P \| Q)$

$$d^2(P_{\underline{X}'}, Q_{\underline{X}'}) = n d^2(P, Q)$$

- Relationship:

$$d^2 \leq D \leq (2 + b) d^2 \text{ if the log density ratio } \leq b.$$

- Redundancy of Two-stage Code:

$$Red_n = \frac{1}{n} E \left\{ \min_q \left[ \log \frac{1}{q(\underline{Y})} + L(q) \right] - \log \frac{1}{p(\underline{Y})} \right\}$$

- bounded by Index of Resolvability:

$$Res_n(p) = \min_q \left\{ D(p||q) + \frac{L(q)}{n} \right\}$$

- Statistical Risk Analysis in i.i.d. case with  $\mathcal{L}(q) = 2L(q)$ :

$$E d^2(p, \hat{p}) \leq \min_q \left\{ D(p||q) + \frac{\mathcal{L}(q)}{n} \right\}$$

- B.85, B.&Cover 91, B., Rissanen, Yu 98, Li 99, Grunwald 07

- Discrepancy between training sample and future

$$Disc(p) = \log \frac{p(\underline{Y})}{q(\underline{Y})} - \log \frac{p(\underline{Y}')}{q(\underline{Y}')}$$

- Future term may be replaced by population counterpart
- Discrepancy control: If  $L(q)$  satisfies the Kraft sum then

$$E \left[ \inf_q \{ Disc(p, q) + 2L(q) \} \right] \geq 0$$

- From which the risk bound follows:

$$\text{Risk} \leq \text{Redundancy} \leq \text{Resolvability}$$

$$E d^2(p, \hat{p}) \leq Red_n \leq Res_n(p)$$

# Statistically valid penalized likelihood

- **Likelihood penalties** arise via
  - number parameters:  $pen(p_\theta) = \lambda \dim(\theta)$
  - roughness penalties:  $pen(p_f) = \lambda \|f^s\|^2$
  - coefficient penalties:  $pen(\theta) = \lambda \|\theta\|_1$
  - Bayes estimators:  $pen(\theta) = \log 1/w(\theta)$
  - Maximum likelihood:  $pen(\theta) = \text{constant}$
  - MDL:
- **Penalized likelihood:**

$$\hat{p} = \arg \min_q \{ \log 1/q(\underline{Y}) + pen(q) \}$$

- Under what condition on the penalty will it be true that the sample based estimate  $\hat{p}$  has risk controlled by the population counterpart?

$$Ed^2(p, \hat{p}) \leq \inf_q \left\{ D(p||q) + \frac{pen(q)}{n} \right\}$$

# Statistically valid penalized likelihood

- Result with J. Li, C. Huang, X. Luo (Festschrift for J. Rissanen 2008)
- **Penalized Likelihood:**

$$\hat{p} = \arg \min_q \left\{ \frac{1}{n} \log \frac{1}{q(\underline{Y})} + \text{pen}_n(q) \right\}$$

- **Penalty condition:**

$$\text{pen}_n(q) \geq \frac{1}{n} \min_{\tilde{q}} \{2L(\tilde{q}) + \Delta_n(p, \tilde{q})\}$$

where the distortion  $\Delta_n(q, \tilde{q})$  is the difference in discrepancies at  $q$  and a representer  $\tilde{q}$

- **Risk conclusion:**

$$Ed^2(p, \hat{q}) \leq \inf_q \{D(p||q) + \text{pen}_n(q)\}$$

- Penalized likelihood

$$\min_{\theta \in \Theta} \left\{ \log \frac{1}{p_{\theta}(\underline{X})} + \text{Pen}(\theta) \right\}$$

- Possibly uncountable  $\Theta$
- Valid codelength interpretation if there exists a countable  $\tilde{\Theta}$  and  $L$  satisfying Kraft such that the above is not less than

$$\min_{\tilde{\theta} \in \tilde{\Theta}} \left\{ \log \frac{1}{p_{\tilde{\theta}}(\underline{X})} + L(\tilde{\theta}) \right\}$$



Equivalently:

- Penalized likelihood with a penalty  $Pen(\theta)$  is information-theoretically valid with uncountable  $\Theta$ , if there is a countable  $\tilde{\Theta}$  and Kraft summable  $L(\tilde{\theta})$ , such that, for every  $\theta$  in  $\Theta$ , there is a representor  $\tilde{\theta}$  in  $\tilde{\Theta}$  such that

$$Pen(\theta) \geq L(\tilde{\theta}) + \log \frac{p_{\theta}(\underline{x})}{p_{\tilde{\theta}}(\underline{x})}$$

- This is the link between uncountable and countable cases

# Statistical-Risk Valid Penalty

- For an uncountable  $\Theta$  and a penalty  $Pen(\theta)$ ,  $\theta \in \Theta$ , suppose there is a countable  $\tilde{\Theta}$  and  $\mathcal{L}(\tilde{\theta}) = 2L(\tilde{\theta})$  where  $L(\tilde{\theta})$  satisfies Kraft, such that, for all  $\underline{x}, \theta^*$ ,

$$\begin{aligned} & \min_{\theta \in \Theta} \left\{ \left[ \log \frac{p_{\theta^*}(\underline{x})}{p_{\theta}(\underline{x})} - d_n^2(\theta^*, \theta) \right] + Pen(\theta) \right\} \\ & \geq \min_{\tilde{\theta} \in \tilde{\Theta}} \left\{ \left[ \log \frac{p_{\theta^*}(\underline{x})}{p_{\tilde{\theta}}(\underline{x})} - d_n^2(\theta^*, \tilde{\theta}) \right] + \mathcal{L}(\tilde{\theta}) \right\} \end{aligned}$$

- Proof of the risk conclusion:  
The second expression has expectation  $\geq 0$ ,  
so the first expression does too.
- B., Li, & Luo (Rissanen Festschrift 2008, Proc. Porto Info Theory Workshop 2008)

# $\ell_1$ Penalties are codelength and risk valid

## Regression Setting: Linear Span of a Dictionary

- $\mathcal{G}$  is a dictionary of candidate basis functions  
E.g. wavelets, splines, polynomials, trigonometric terms, sigmoids, explanatory variables and their interactions
- Candidate functions in the linear span  
$$f_\theta(x) = \sum_{g \in \mathcal{G}} \theta_g g(x)$$
- weighted  $\ell_1$  norm of coefficients  $\|\theta\|_1 = \sum_g a_g |\theta_g|$
- weights  $a_g = \|g\|_n$  where  $\|g\|_n^2 = \frac{1}{n} \sum_{i=1}^n g^2(x_i)$
- Regression  $p_\theta(y|x) = \text{Normal}(f_\theta(x), \sigma^2)$
- $\ell_1$  Penalty (Lasso, Basis Pursuit)

$$\text{pen}(\theta) = \lambda \|\theta\|_1$$

# Regression with $\ell_1$ penalty

- $\ell_1$  penalized log-density estimation, i.i.d. case

$$\hat{\theta} = \operatorname{argmin}_{\theta} \left\{ \frac{1}{n} \log \frac{1}{p_{f_{\theta}}(\underline{x})} + \lambda_n \|\theta\|_1 \right\}$$

- Regression with Gaussian model

$$\min_{\theta} \left\{ \frac{1}{2\sigma^2} \frac{1}{n} \sum_{i=1}^n (Y_i - f_{\theta}(x_i))^2 + \frac{1}{2} \log 2\pi\sigma^2 + \frac{\lambda_n}{\sigma} \|\theta\|_1 \right\}$$

- Codelength Valid and Risk Valid for

$$\lambda_n \geq \sqrt{\frac{2 \log(2p)}{n}} \quad \text{with } p = \operatorname{Card}(\mathcal{G})$$

# Adaptive risk bound specialized to regression

- Again for fixed design and  $\lambda_n = \sqrt{\frac{2 \log 2p}{n}}$ , multiplying through by  $4\sigma^2$ ,

$$E\|f^* - f_{\hat{\theta}}\|_n^2 \leq \inf_{\theta} \left\{ 2\|f^* - f_{\theta}\|_n^2 + 4\sigma\lambda_n\|\theta\|_1 \right\}$$

- In particular for all targets  $f^* = f_{\theta^*}$  with finite  $\|\theta^*\|$  the risk bound  $4\sigma\lambda_n\|\theta^*\|$  is of order  $\sqrt{\frac{\log M}{n}}$
- Details in Barron, Luo (proceedings Workshop on Information Theory Methods in Science & Eng. 2008), Tampere, Finland

- The variable complexity cover property is demonstrated by choosing the representer  $\tilde{f}$  of  $f_\theta$  of the form

$$\tilde{f}(x) = \frac{v}{m} \sum_{k=1}^m g_k(x)$$

- $g_1, \dots, g_m$  picked at random from  $\mathcal{G}$ , independently, where  $g$  arises with probability proportional to  $|\theta_g|$

- **Achieving Shannon Capacity:** (with A. Joseph, S. Cho)
  - Gaussian Channel with Power Constraints
  - History of Methods
  - Communication by Regression
  - Sparse Superposition Coding
  - Adaptive Successive Decoding
  - Rate, Reliability, and Computational Complexity

# Shannon Formulation

- Input bits:  $u = (u_1, u_2, \dots, u_K)$



- Encoded:  $x = (x_1, x_2, \dots, x_n)$



- Channel:  $p(y|x)$



- Received:  $y = (y_1, y_2, \dots, y_n)$



- Decoded:  $\hat{u} = (\hat{u}_1, \hat{u}_2, \dots, \hat{u}_K)$

- **Rate:**  $R = \frac{K}{n}$                       **Capacity**  $C = \max I(X; Y)$

- **Reliability:** Want small  $\text{Prob}\{\hat{u} \neq u\}$   
and small  $\text{Prob}\{\text{Fraction mistakes} \geq \alpha\}$



# Gaussian Noise Channel

- Input bits:  $u = (u_1, u_2, \dots, u_K)$



- Encoded:  $x = (x_1, x_2, \dots, x_n)$      $\text{ave } \frac{1}{n} \sum_{i=1}^n x_i^2 \leq P$



- Channel:             $p(y|x)$              $y = x + \varepsilon \quad \varepsilon \sim N(0, \sigma^2 I)$



- Received:  $y = (y_1, y_2, \dots, y_n)$



- Decoded:  $\hat{u} = (\hat{u}_1, \hat{u}_2, \dots, \hat{u}_K)$

- Rate:  $R = \frac{K}{n}$                              $\text{Capacity } C = \frac{1}{2} \log(1 + P/\sigma^2)$

- Reliability: Want small  $\text{Prob}\{\hat{u} \neq u\}$   
and small  $\text{Prob}\{\text{Fraction mistakes} \geq \alpha\}$

# Shannon Theory meets Coding Practice

- The Gaussian noise channel is the basic model for
  - wireless communication  
radio, cell phones, television, satellite, space
  - wired communication  
internet, telephone, cable
- Forney and Ungerboeck 1998 review
  - modulation, coding, and shaping for the Gaussian channel
- Richardson and Urbanke 2008 cover much of the state of the art in the analysis of coding
  - There are fast encoding and decoding algorithms, with empirically good performance for LDPC and turbo codes
  - Some tools for their theoretical analysis, but obstacles remain for mathematical proof of these schemes achieving rates up to capacity for the Gaussian channel
- Arikan 2009, Arikan and Teletar 2009 polar codes
  - Adapting polar codes to Gaussian channel (Abbe and B. 2011)
- Method here is different. Prior knowledge of the above is not necessary to follow what we present.

# Sparse Superposition Code

- **Input bits:**  $u = (u_1 \dots \dots \dots u_K)$
- **Coefficients:**  $\beta = (00 * 0000000000 * 00 \dots 0 * 000000)^T$
- **Sparsity:**  $L$  entries non-zero out of  $N$
- **Matrix:**  $X$ ,  $n$  by  $N$ , all entries indep Normal(0, 1)
- **Codeword:**  $X\beta$ , superposition of a subset of columns
- **Receive:**  $y = X\beta + \varepsilon$ , a statistical linear model
- **Decode:**  $\hat{\beta}$  and  $\hat{u}$  from  $X, y$

# Sparse Superposition Code

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- **Receive:**  $y = X\beta + \varepsilon$
- **Decode:**  $\hat{\beta}$  and  $\hat{u}$  from  $X, y$
- **Rate:**  $R = \frac{K}{n}$  from  $K = \log \binom{N}{L}$ , near  $L \log \left(\frac{N}{L} e\right)$

# Sparse Superposition Code

- **Input bits:**  $u = (u_1 \dots \dots \dots u_K)$
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- **Reliability:** small  $\text{Prob}\{\text{Fraction } \hat{\beta} \text{ mistakes} \geq \alpha\}$ , small  $\alpha$

# Sparse Superposition Code

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- **Reliability:** small Prob{*Fraction  $\hat{\beta}$  mistakes*  $\geq \alpha$ }, small  $\alpha$
- **Outer RS code:** rate  $1 - 2\alpha$ , corrects remaining mistakes
- **Overall rate:**  $R_{tot} = (1 - 2\alpha)R$

# Sparse Superposition Code

- **Input bits:**  $u = (u_1 \dots \dots \dots u_K)$
- **Coefficients:**  $\beta = (00 * 0000000000 * 00 \dots 0 * 000000)^T$
- **Sparsity:**  $L$  entries non-zero out of  $N$
- **Matrix:**  $X$ ,  $n$  by  $N$ , all entries indep Normal(0, 1)
- **Codeword:**  $X\beta$
- **Receive:**  $y = X\beta + \varepsilon$
- **Decode:**  $\hat{\beta}$  and  $\hat{u}$  from  $X, y$
- **Rate:**  $R = \frac{K}{n}$  from  $K = \log \binom{N}{L}$
- **Reliability:** small Prob{*Fraction  $\hat{\beta}$  mistakes*  $\geq \alpha$ }, small  $\alpha$
- **Outer RS code:** rate  $1 - 2\alpha$ , corrects remaining mistakes
- **Overall rate:**  $R_{tot} = (1 - 2\alpha)R$ .

Is it reliable with rate up to capacity?

# Partitioned Superposition Code

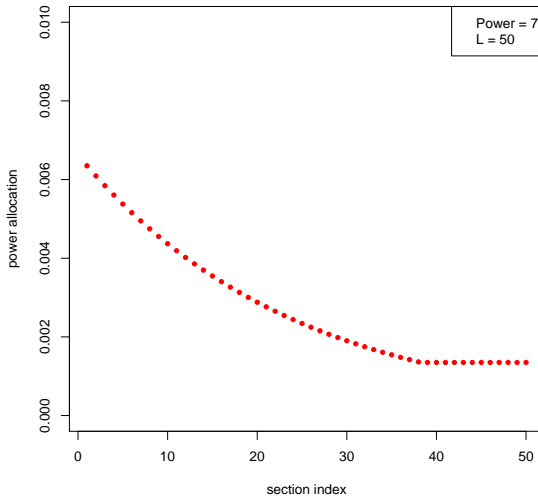
- **Input bits:**  $u = (u_1 \dots, \dots, \dots, \dots u_K)$
- **Coefficients:**  $\beta = (00 * 00000, 00000 * 00, \dots, 0 * 000000)$
- **Sparsity:**  $L$  sections, each of size  $B = N/L$ , a power of 2.  
1 non-zero entry in each section
- **Indices of nonzeros:**  $(j_1, j_2, \dots, j_L)$  directly specified by  $u$
- **Matrix:**  $X$ ,  $n$  by  $N$ , splits into  $L$  sections
- **Codeword:**  $X\beta$
- **Receive:**  $y = X\beta + \varepsilon$
- **Decode:**  $\hat{\beta}$  and  $\hat{u}$
- **Rate:**  $R = \frac{K}{n}$  from  $K = L \log \frac{N}{L} = L \log B$   
may set  $B = n$  and  $L = nR / \log n$
- **Reliability:** small  $\text{Prob}\{\text{Fraction } \hat{\beta} \text{ mistakes} \geq \alpha\}$
- **Outer RS code:** Corrects remaining mistakes
- **Overall rate:** up to capacity?



# Power Allocation

- **Coefficients:**  $\beta = (00*00000, 00000*00, \dots, 0*000000)$
- **Indices of nonzeros:**  $sent = (j_1, j_2, \dots, j_L)$
- **Coeff. values:**  $\beta_{j_\ell} = \sqrt{P_\ell}$  for  $\ell = 1, 2, \dots, L$
- **Power control:**  $\sum_{\ell=1}^L P_\ell = P$
- **Codewords:**  $X\beta$ , have average power  $P$
- **Power Allocations**
  - **Constant power:**  $P_\ell = P/L$
  - **Variable power:**  $P_\ell$  proportional to  $u_\ell = e^{-2C\ell/L}$
  - **Variable with leveling:**  $P_\ell$  proportional to  $\max\{u_\ell, cut\}$

# Power Allocation



# Contrast Two Decoders

Decoders using received  $y = X\beta + \varepsilon$

Optimal: **Least Squares Decoder**

$$\hat{\beta} = \operatorname{argmin} \|Y - X\beta\|^2$$

- minimizes probability of error with uniform input distribution
- reliable for all  $R < C$ , with best form of error exponent

Practical: **Adaptive Successive Decoder**

- fast decoder
- reliable using variable power allocation for all  $R < C$

## Decoding Steps

- **Start:** [Step 1]
  - Compute the inner product of  $Y$  with each column of  $X$
  - See which are above a threshold
  - Form initial fit as weighted sum of columns above threshold
- **Iterate:** [Step  $k \geq 2$ ]
  - Compute the inner product of residuals  $Y - Fit_{k-1}$  with each remaining column of  $X$
  - See which are above threshold
  - Add these columns to the fit
- **Stop:**
  - At Step  $k = \log B$ , or
  - if there are no inner products above threshold

# Decoding Progression

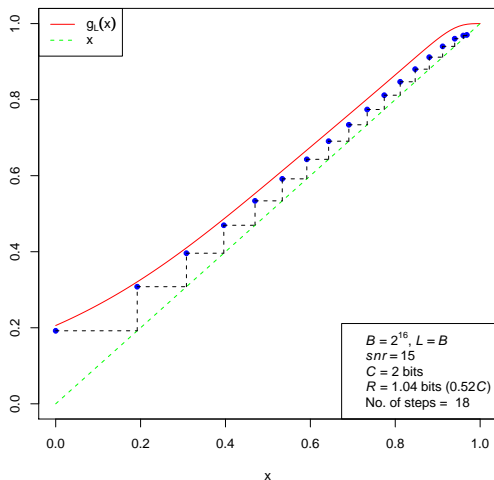


Figure : Plot of likely progression of weighted fraction of correct detections  $\hat{q}_{1,k}$ , for  $snr = 15$ .

# Decoding Progression

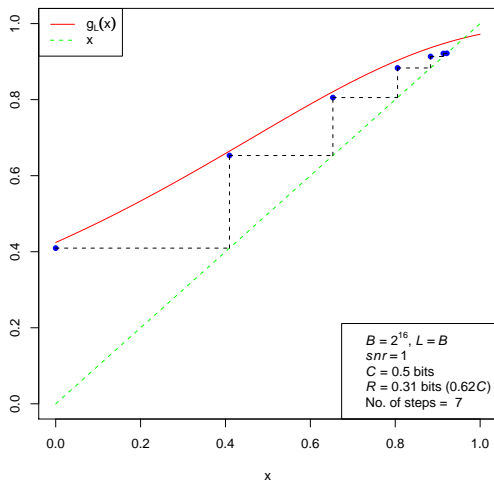


Figure : Plot of of likely progression of weighted fraction of correct detections  $\hat{q}_{1,k}$ , for  $snr = 1$ .

# Rate and Reliability

**Optimal:** Least squares decoder of sparse superposition code

- Prob error **exponentially small in  $n$**  for small  $\Delta = C - R > 0$

$$\text{Prob}\{\text{Error}\} \leq e^{-n(C-R)^2/2V}$$

- In agreement with the Shannon-Gallager optimal exponent, though with possibly suboptimal  $V$  depending on the  $snr$

**Practical:** Adaptive Successive Decoder, with outer RS code.

- **achieves rates up to  $C_B$  approaching capacity**

$$C_B = \frac{C}{1 + c_1/\log B}$$

- Probability **exponentially small in  $L$**  for  $R \leq C_B$

$$\text{Prob}\{\text{Error}\} \leq e^{-L(C_B-R)^2 c_2}$$

- Improves to  $e^{-c_3 L (C_B - R)^2 (\log B)^{0.5}}$  using a Bernstein bound.
- Nearly optimal when  $C_B - R$  is of the same order as  $C - C_B$ .
- Our  $c_1$  is near  $(2.5 + 1/snr) \log \log B + 4C$

- Sparse superposition coding is fast and reliable at rates up to channel capacity
- Formulation and analysis blends modern statistical regression and information theory